



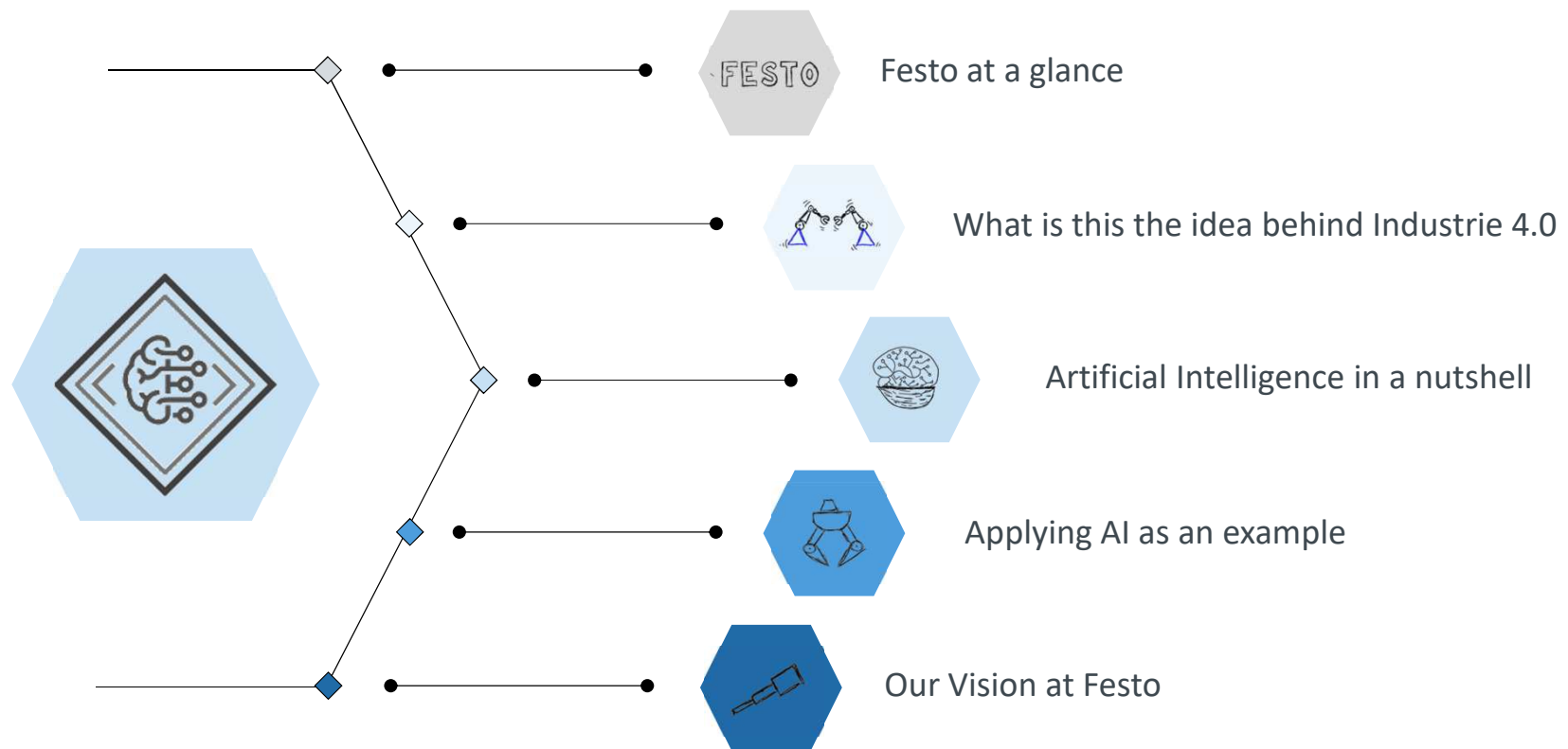
# Innovative new areas of use of AI and ML in the Manufacturing Industry

Presented by: **Dr. Stefan Elmer**

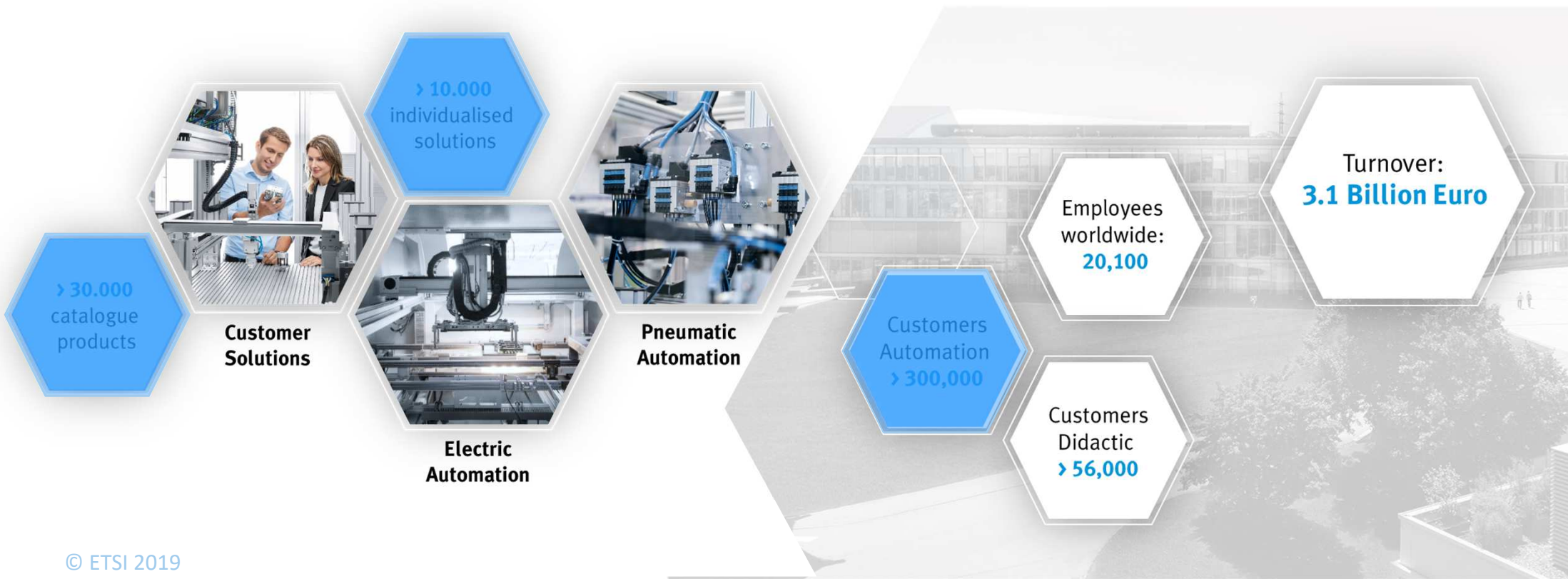
For: **ETSI Summit on Artificial Intelligence**

04.04.2019

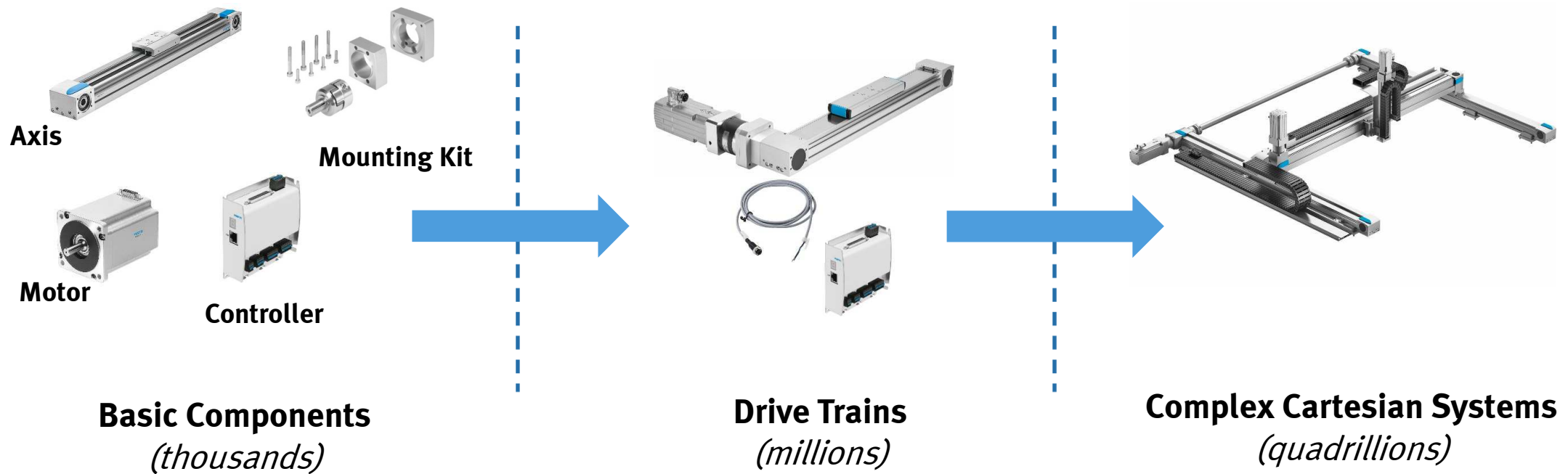
# Structure

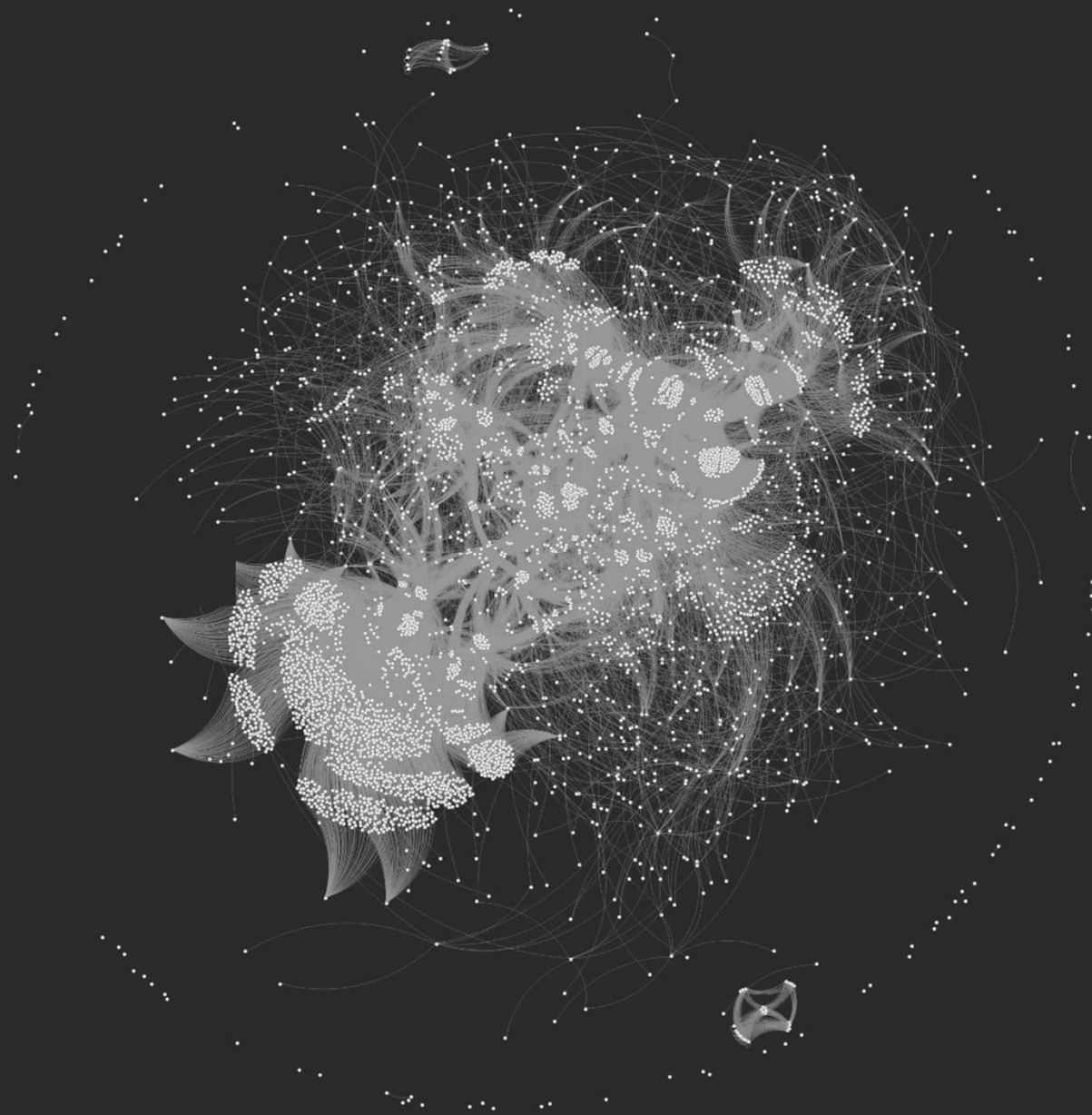


# Festo at a glance



# It's a complex world we live in...







**FESTO**

Entdecken Sie höchste Produktivität!

**→ WE ARE THE ENGINEERS  
OF PRODUCTIVITY.**

# Longterm evolution of our Digital Solutions to an I4.0 Full Service Portfolio for OEM & End User

FESTO

OEM

“We make machines ready for industry 4.0”

END USER

“We maximize the OEE through digital industry solutions”

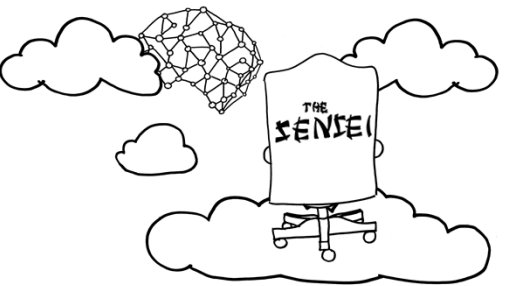
Engineering

Commissioning

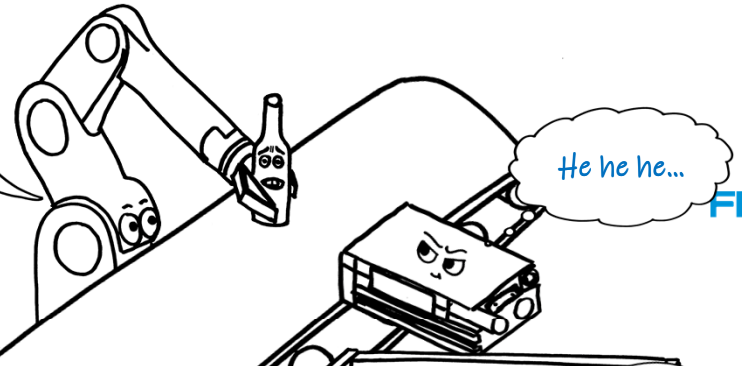
Operation

Maintenance

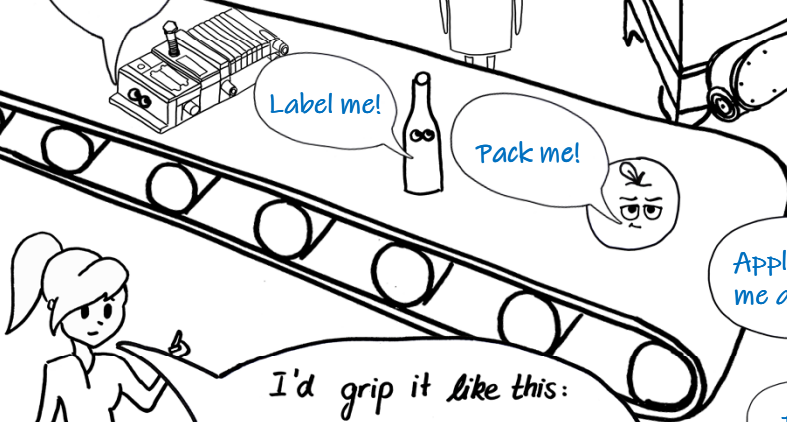
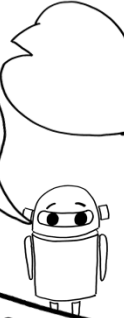




I spy with my little eye...  
If you just held still, I promise it won't hurt...




I've got a screw loose  
Do you want me to ask the Sensei in the cloud?

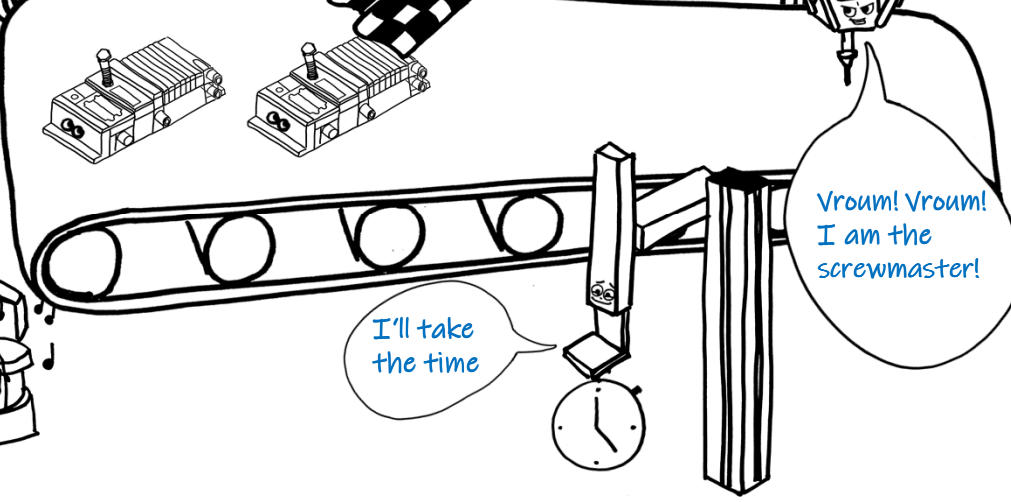
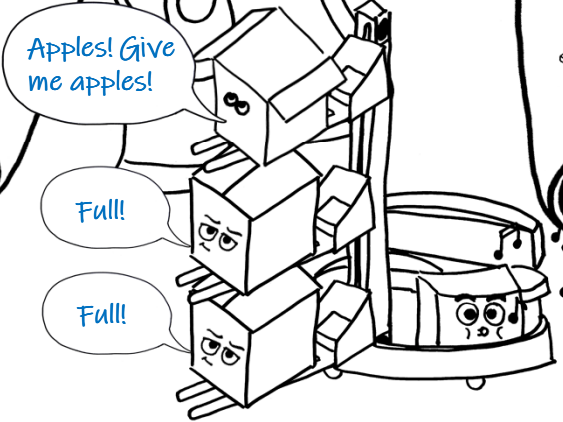


I don't know what to wear...

Let the battle commence

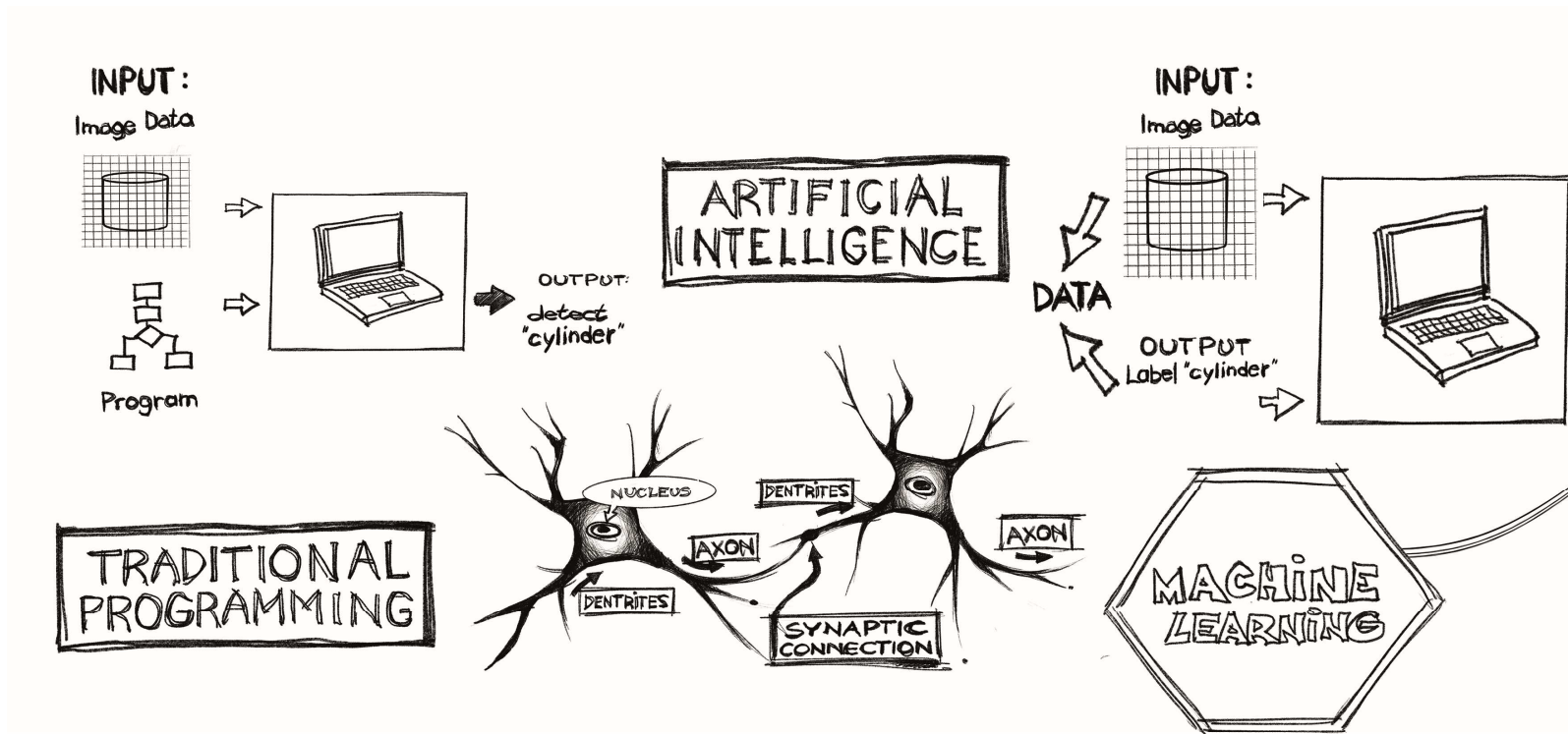


I'd grip it like this:  
  
Why don't you learn from me?

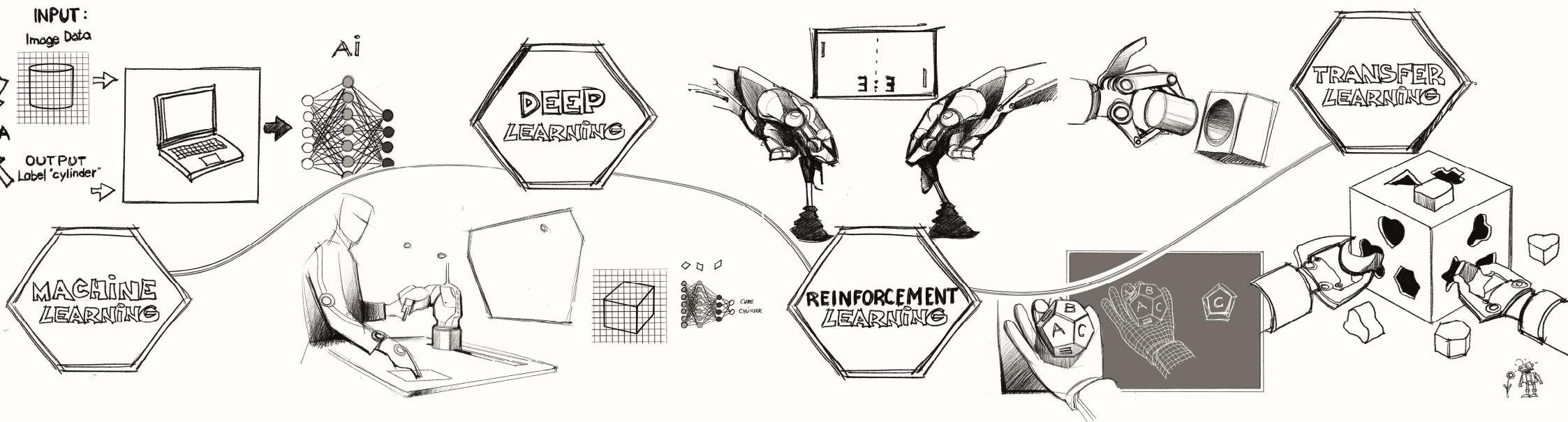




# Speaking of Artificial Intelligence...

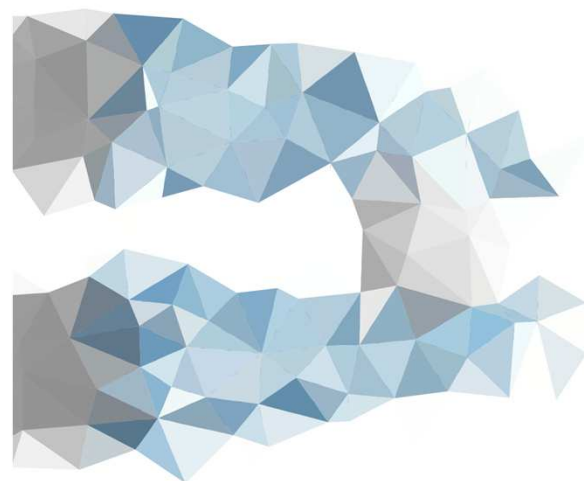


# The Evolution of Machine Learning

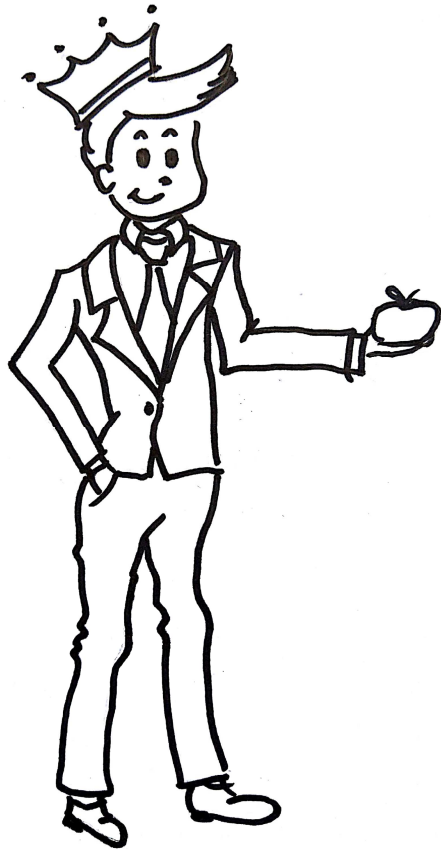


## Applying AI...

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Festo  
GripperAI



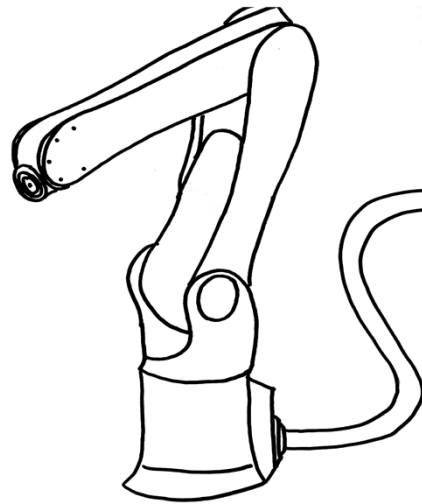
This is Tom  
Tom has an apple..

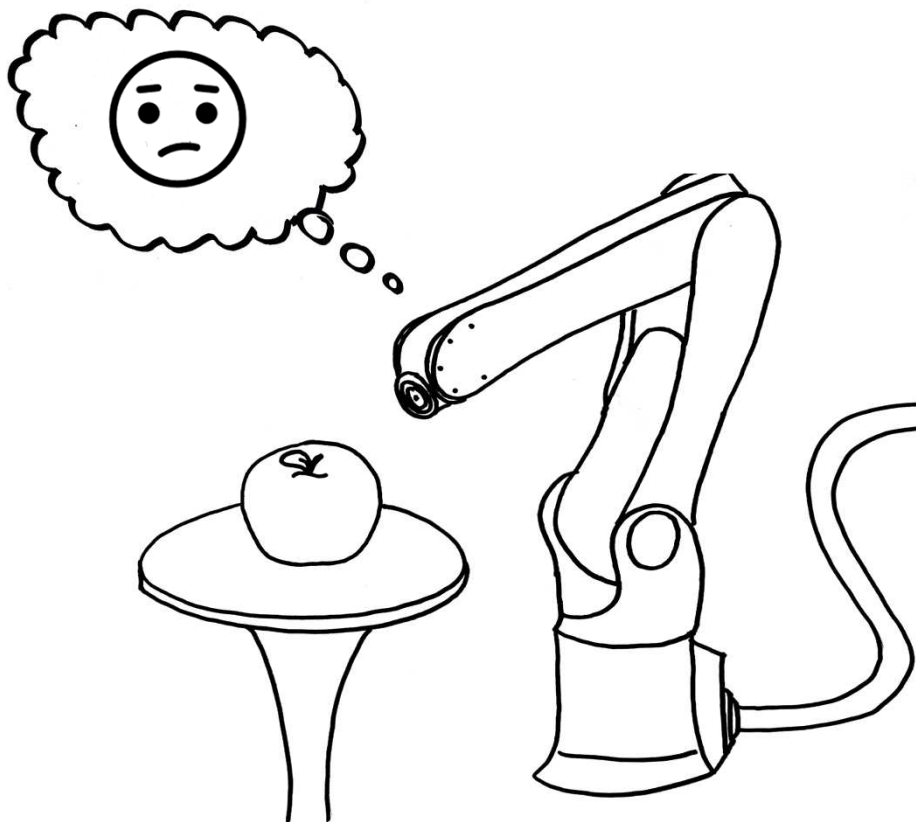




This is Tom  
Tom has an apple  
Tom wants his robot to grasp the apple  
His robot is named Frank

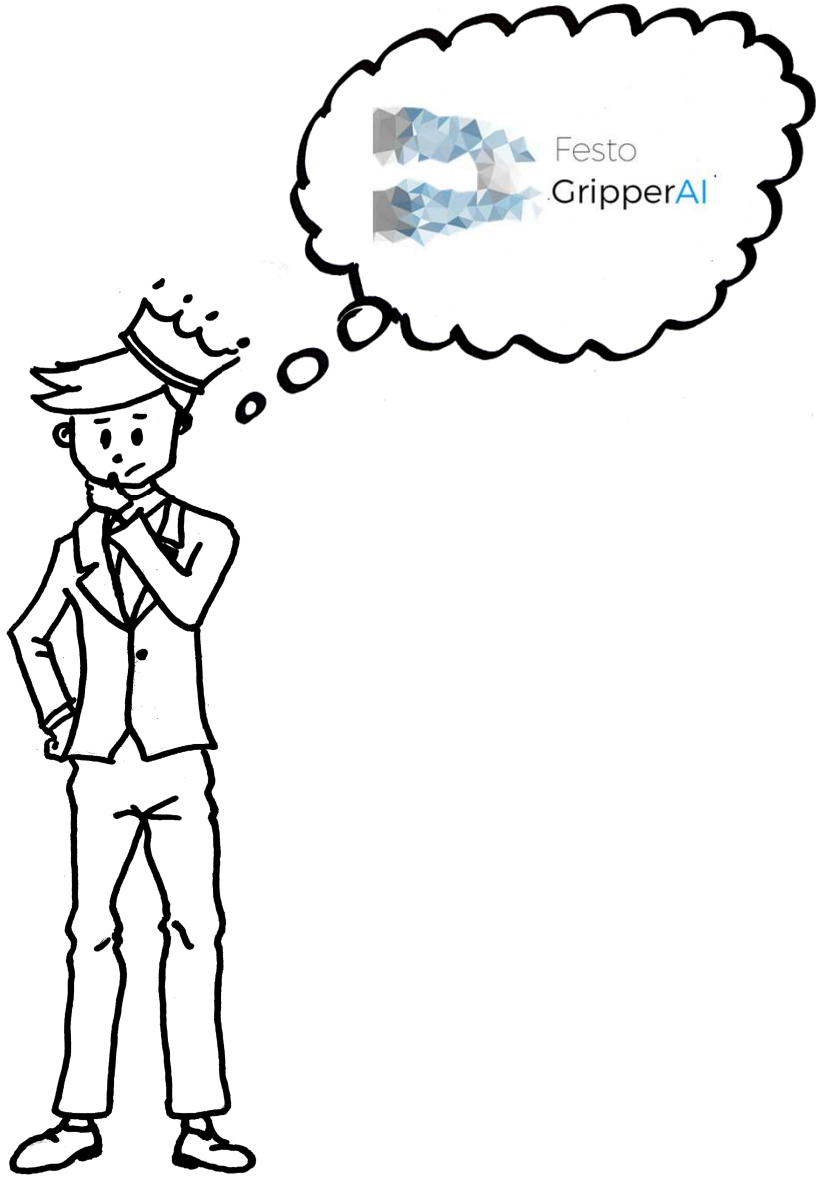
This is Frank...





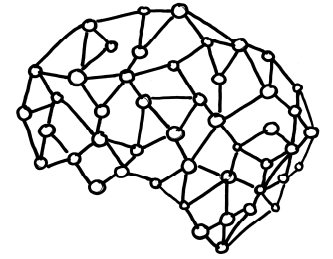
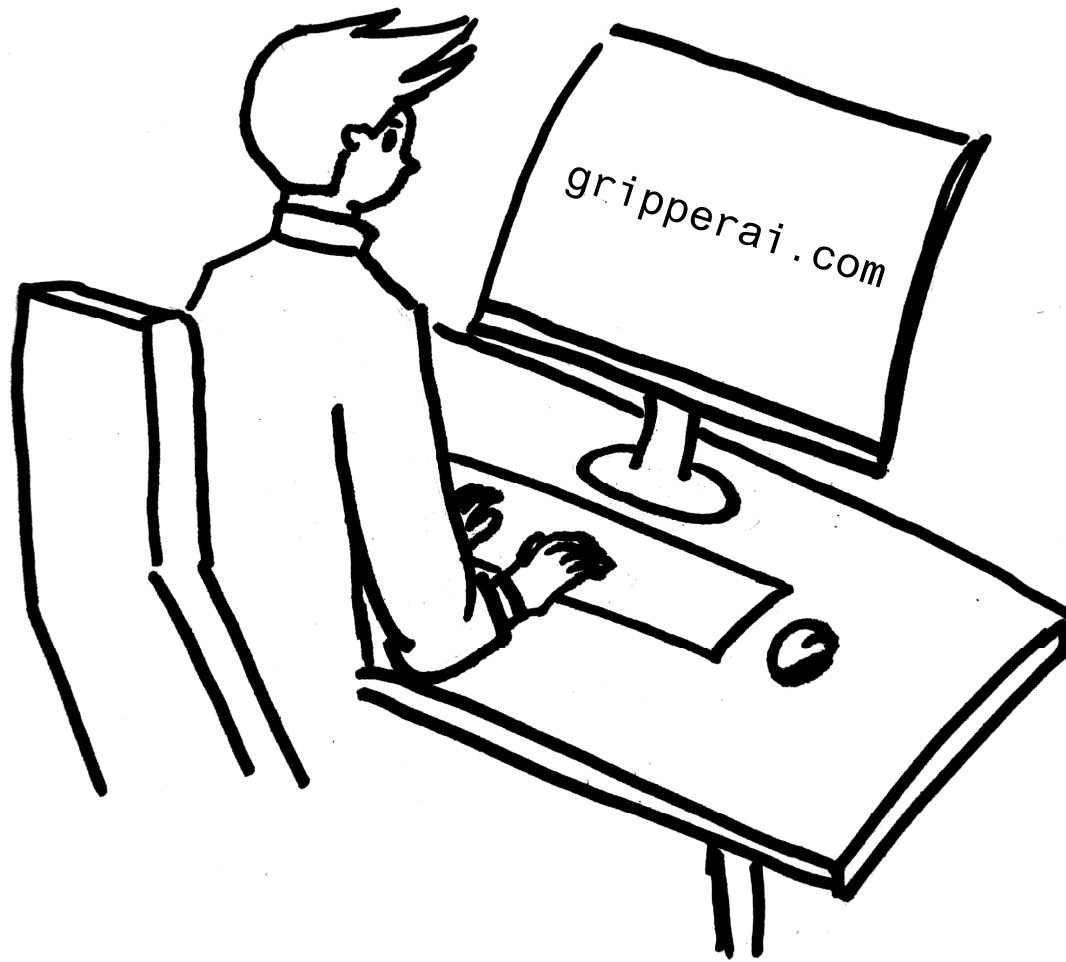
Frank doesn't know what an apple is  
Frank can not grasp an apple  
Frank is confused..



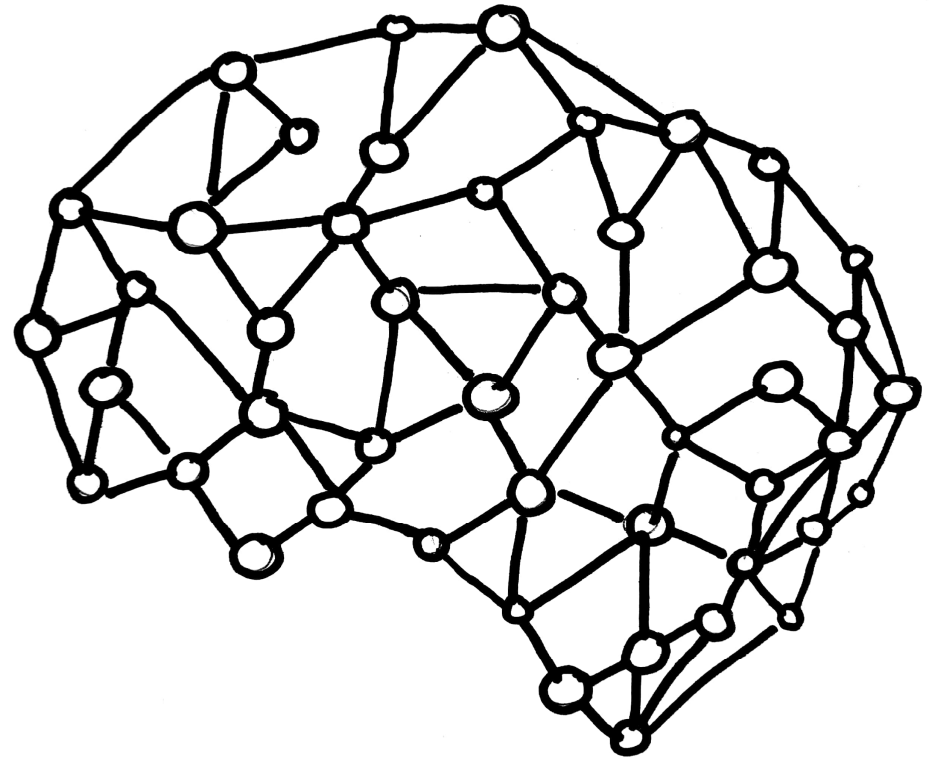
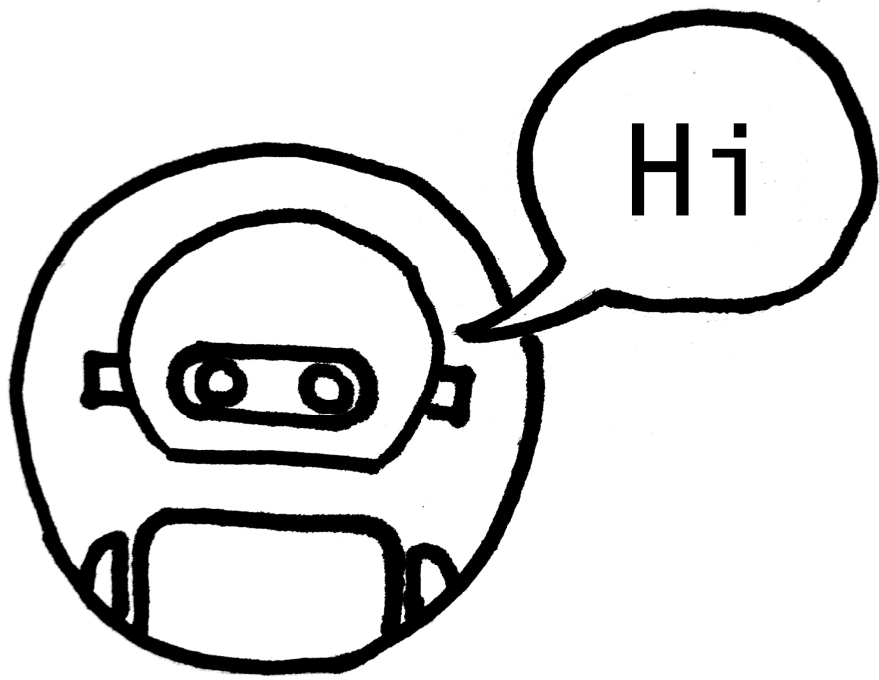


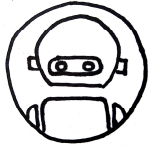
Tom heard about Festo's new GripperAI





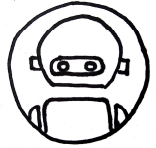






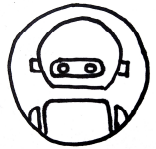
How can I help you?

I want my robot to grasp an apple



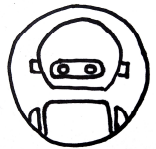
Great... I know what an apple is.  
How do you want to grasp your apple?

It should be placed upside down after  
handling it and has a sensible surface.

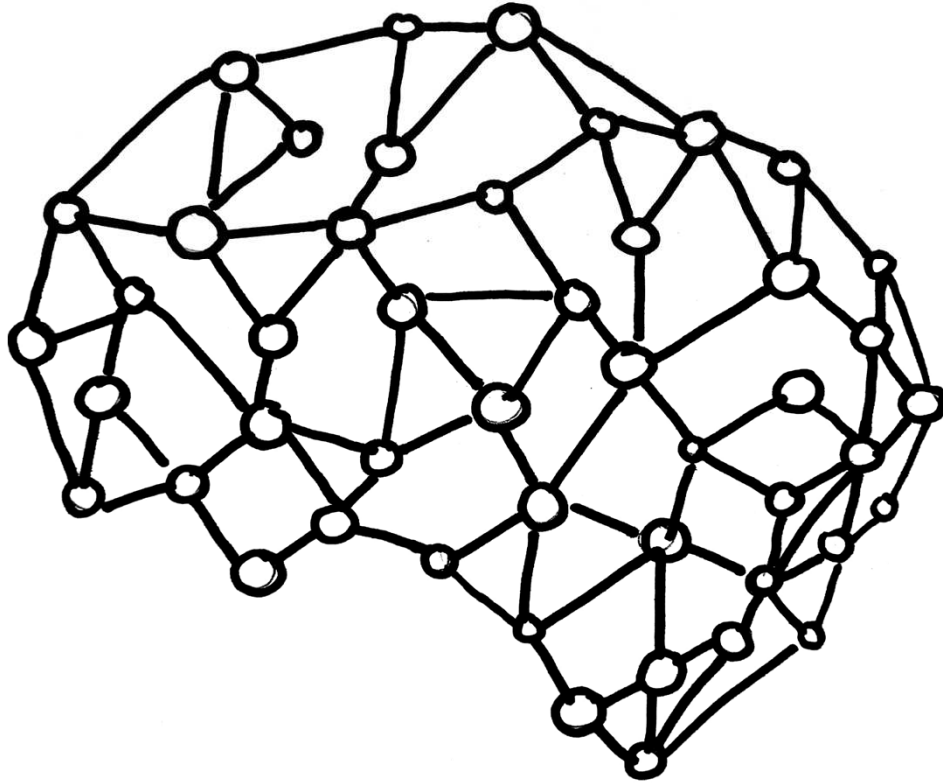
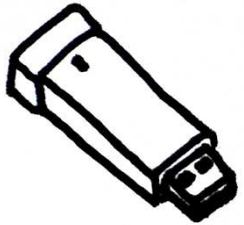
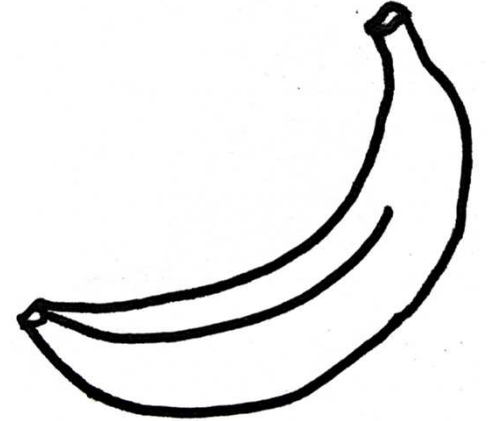
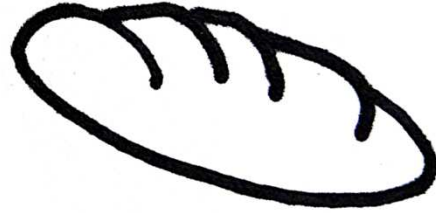


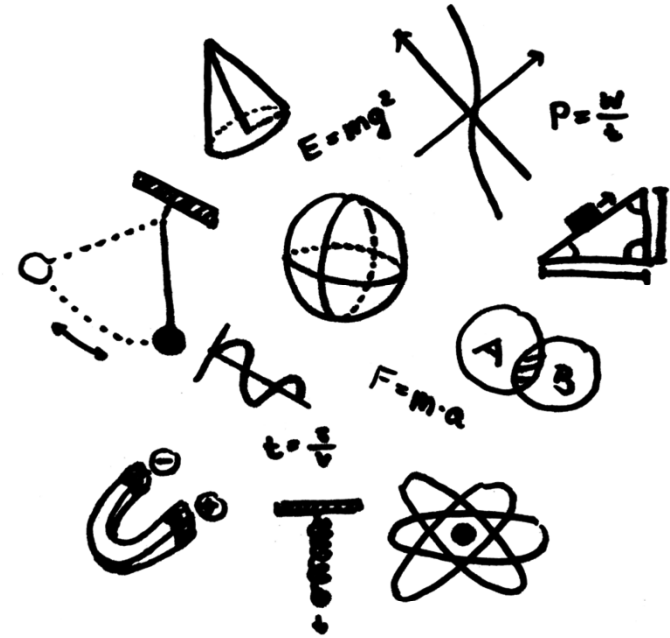
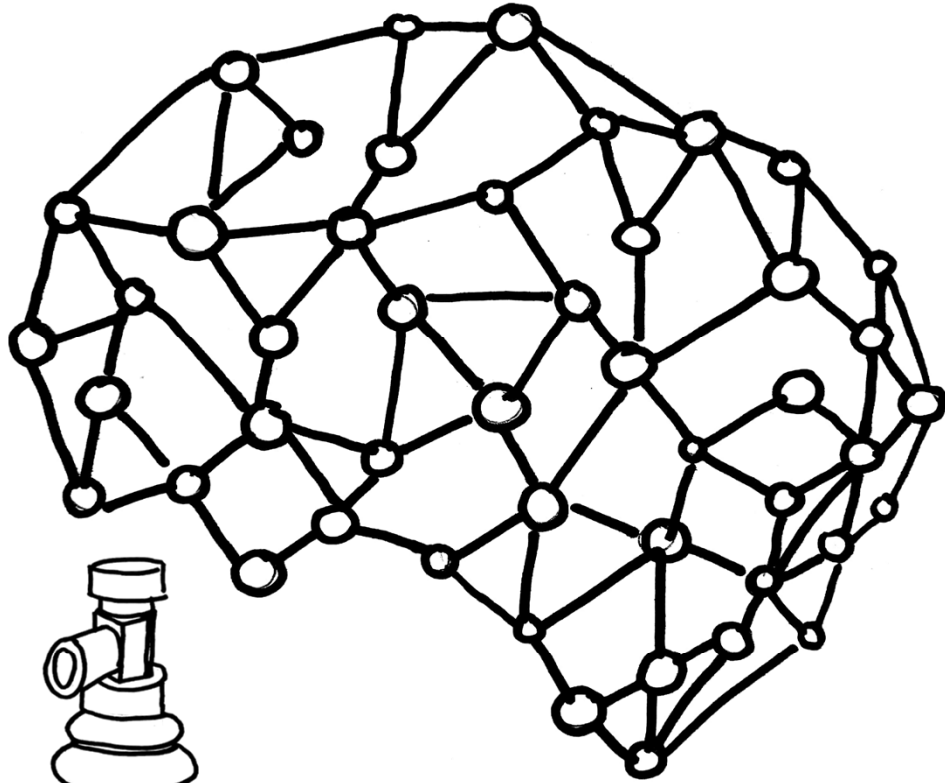
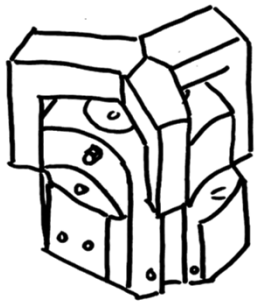
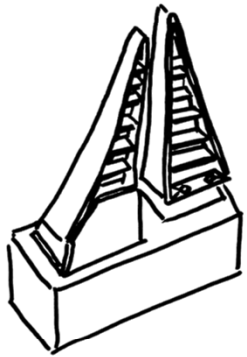
Okay, understood.  
What kind of robot do you want to use?

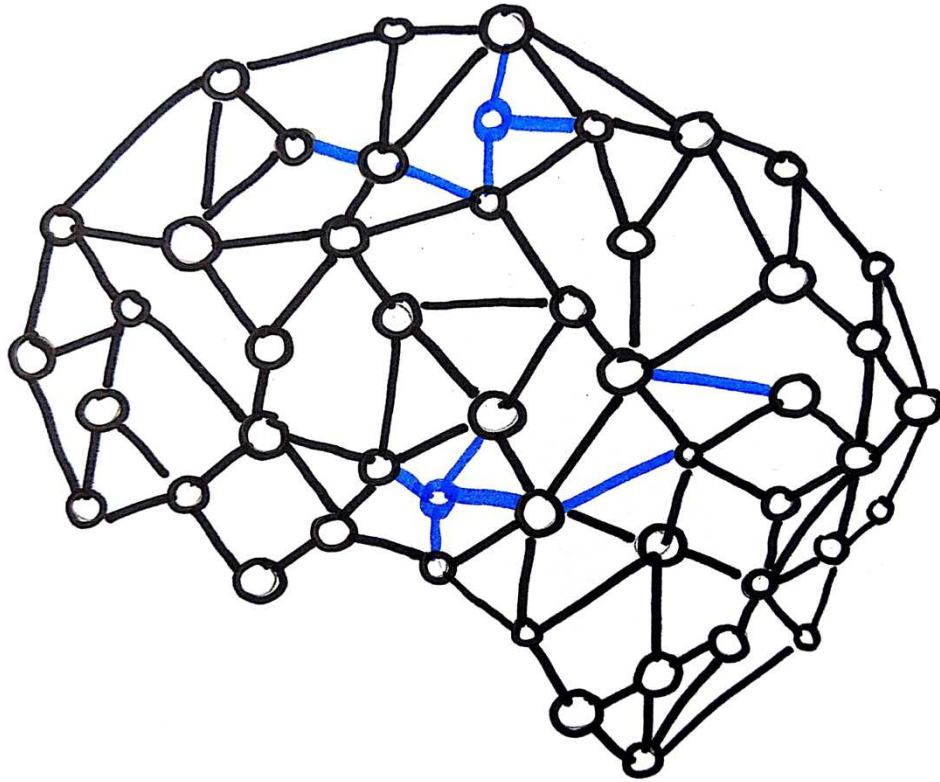
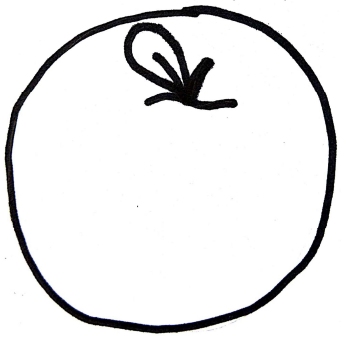
I have Frank.

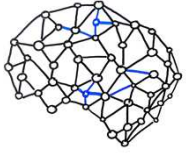


I know Frank! He's a great guy! I don't want him to be confused.  
Let me check that.









I now know how Frank can grasp an apple  
Frank needs two Finray Fingers

> type: DHAS

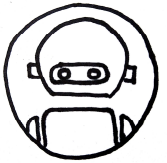
Frank needs a parallel Gripper with long stroke

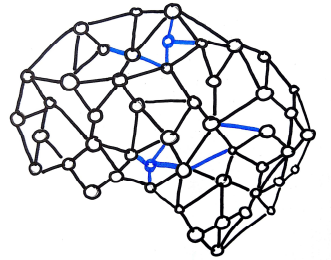
> type: HGPL

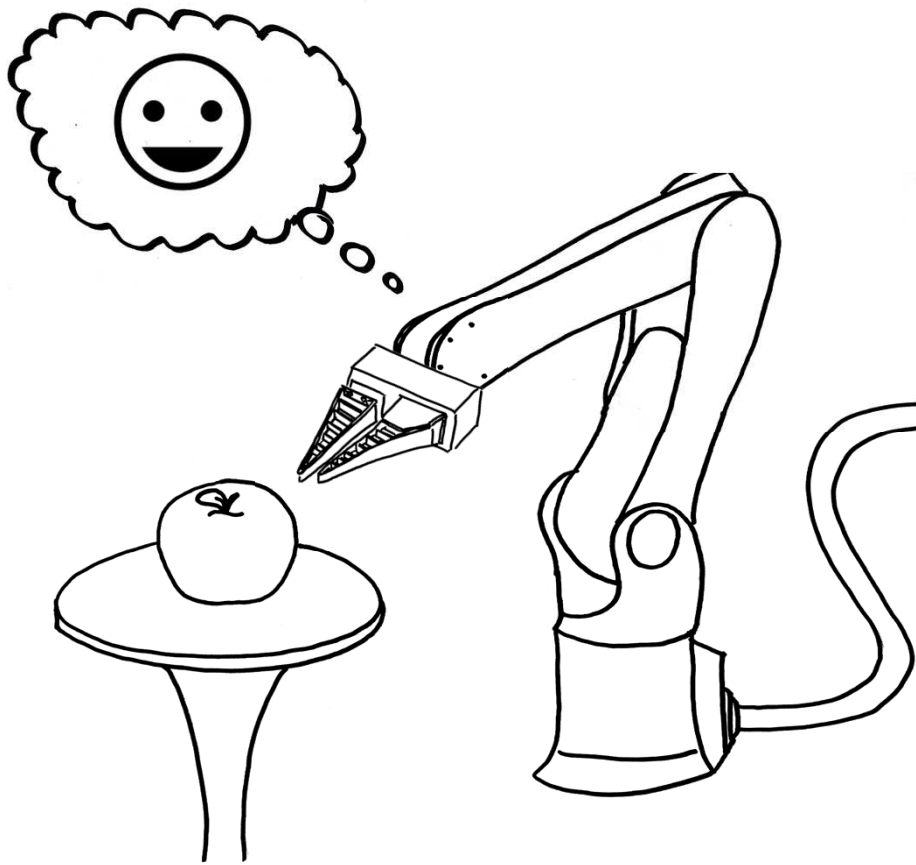
Frank can use the following control code

> motion\_control.py

Thanks GripperAI!  
I'll tell Tom!







Thanks to GripperAI Frank now knows what an apple is

Frank now knows how to recognize and grasp an apple (and an orange,...)

Frank is happy...







Thanks to GripperAI Frank now knows what an apple is

Frank now knows how to recognize and grasp an apple (and an orange,...)

Frank is happy...

If Frank is happy, Tom is happy

If Tom is happy, **FESTO** is happy!

**WHAT is then next STEP?**

**COMBINING**  
**Artificial Intelligence**  
**with Human Skills**



<https://www.youtube.com/watch?v=5e0F14IRxVc>

This Presentation was supported by:

Kathrin Evers  
Dr. Jan R. Seyler  
Simone Mangold  
Dionysios Satikidis  
Dr. Elias Knubben  
& the Festo Bionik Team

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