

9th
UCAAT *User Conference on
Advanced Automated Testing*

Identifying and Classifying **Uncertainties**
to support **Testing of Industrial Elevators**

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simula



Industry Context



- Develop and maintain elevators
- SiL testing



Elevator attributes

- Safety
- Quality of service (QoS)
- ...

Elevate

- Performance analysis
- Simulation with visual display
- Building, elevator and passenger data



Time (hrs:min:sec)	00:02:43	Direction	-	-	Λ
AWT (s)	8.8	Position (m)	0.00	22.80	0.02
ATT (s)	18.6	Speed (m/s)	0.00	0.00	0.13
		Load (kg)	0	0	0
Floor Name	People Waiting	Landing Calls	Car 1	Car 2	Car 3
Level 8	0				
Level 7	0				
Level 6	0				
Level 5	0				
Level 4	0				
Level 3	0				
Level 2	1	▲			
Level 1	0				

What uncertainties do elevators face?

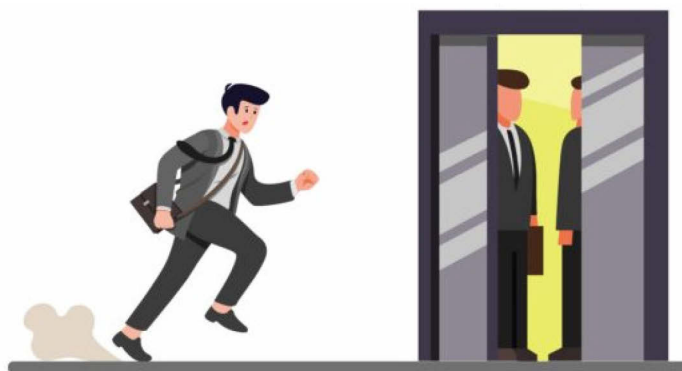
Uncertainties

Hardware

- Start delay
- Door dwell
- ...

Passenger

- Attributes (e.g., Mass)
- Behaviors (e.g., Arrival, Loading and Unloading)



Rush to an elevator



Uncertain destination



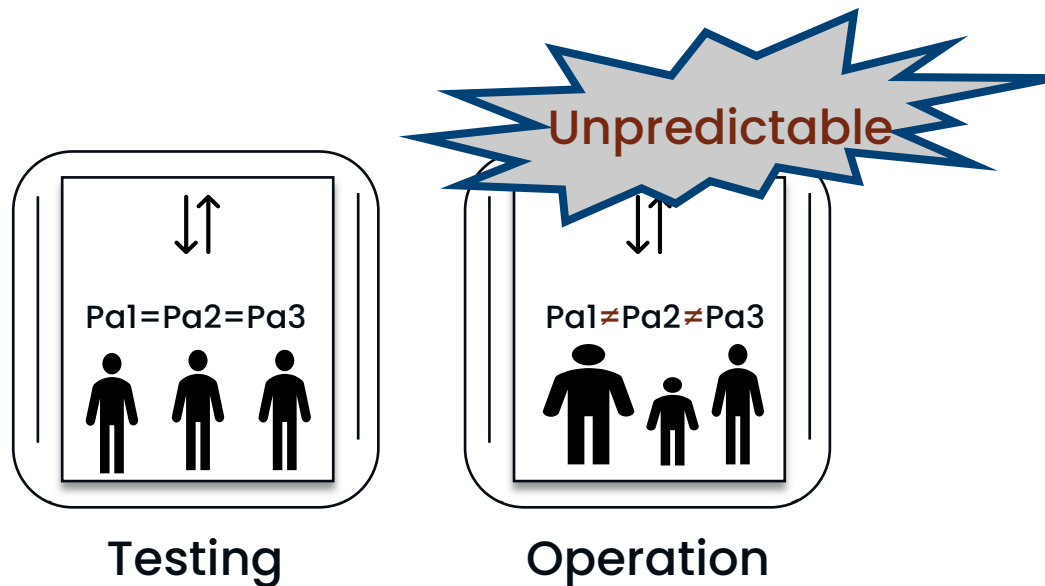
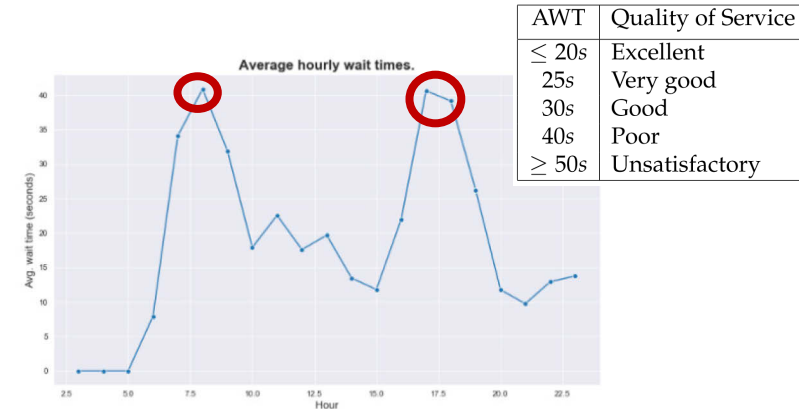
Block the door

How to **cost-effectively** test elevators in the presence of **uncertainties** to ensure their **dependability**?

Practices and Challenges

Practices

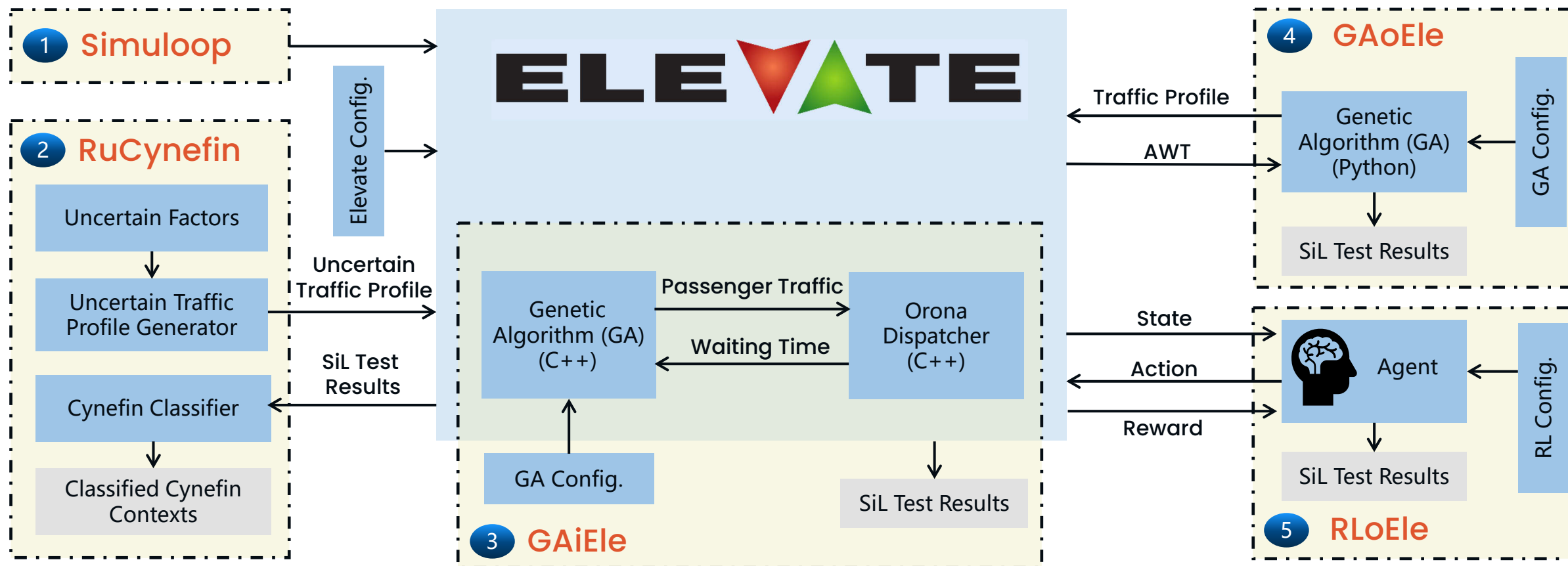
- SiL testing with Elevate manually
- Fixed passenger attributes (e.g., mass)
- Lack of testing of SUT under uncertainty



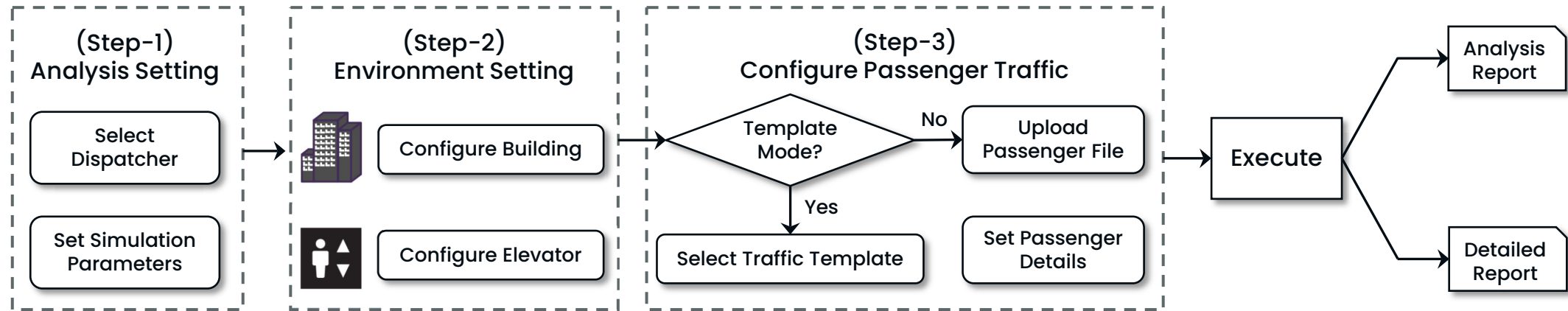
Challenges

- Automate SiL ➡ **Simuloop**
- Classify passenger uncertainties ➡ **RuCynefin**
- Search and RL based testing of elevators under uncertainty ➡ **GAiEle & GAOEle & RLoEle**

Our SiL-based Methods

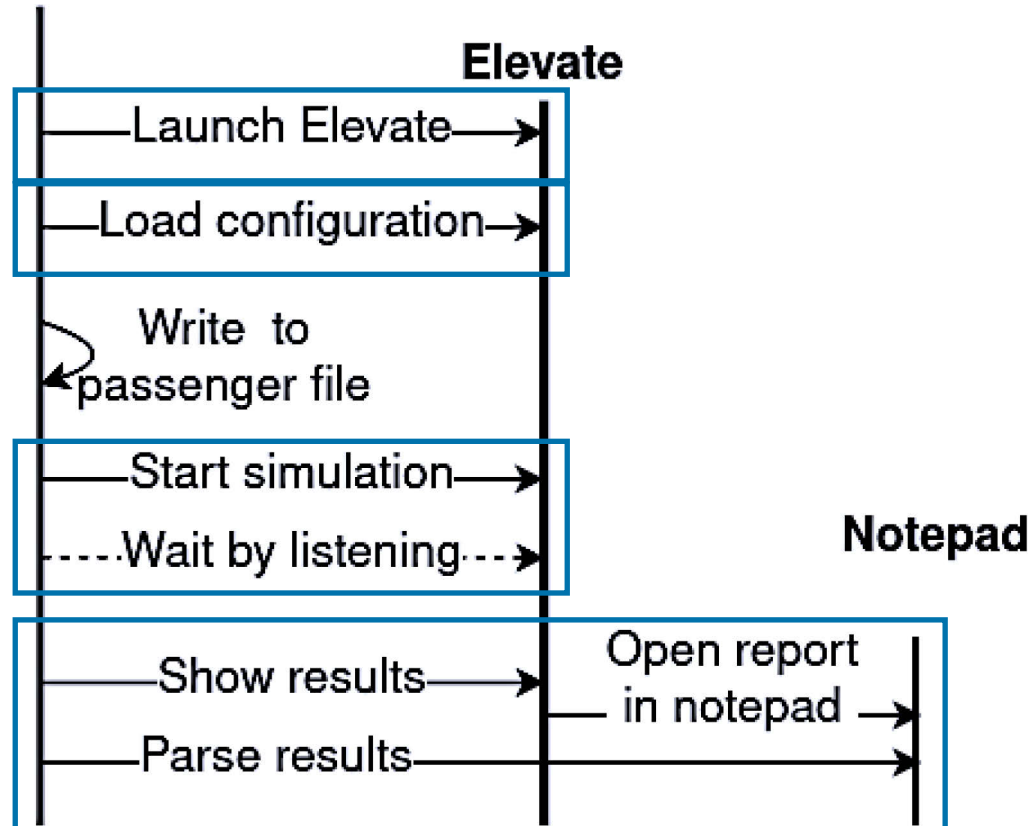


SiL with Elevate



Simuloop: Automate SiL

Simuloop



Terminal output:

```

(env) PS C:\Users\torbj\Desktop\elevate_debug> python .\main.py
(env) PS C:\Users\torbj\Desktop\elevate_debug> python .\main.py
(env) PS C:\Users\torbj\Desktop\elevate_debug> python .\main.py
  
```

Elevate - [elevate_group] interface:

Page: 1 of 3
 Job: [blank]
 Job No: [blank]
 Calculation Title: [blank]
 Made By: [blank]
 Check By: [blank]
 File Date: elevate_group 11 Jun 2021 16:19:22

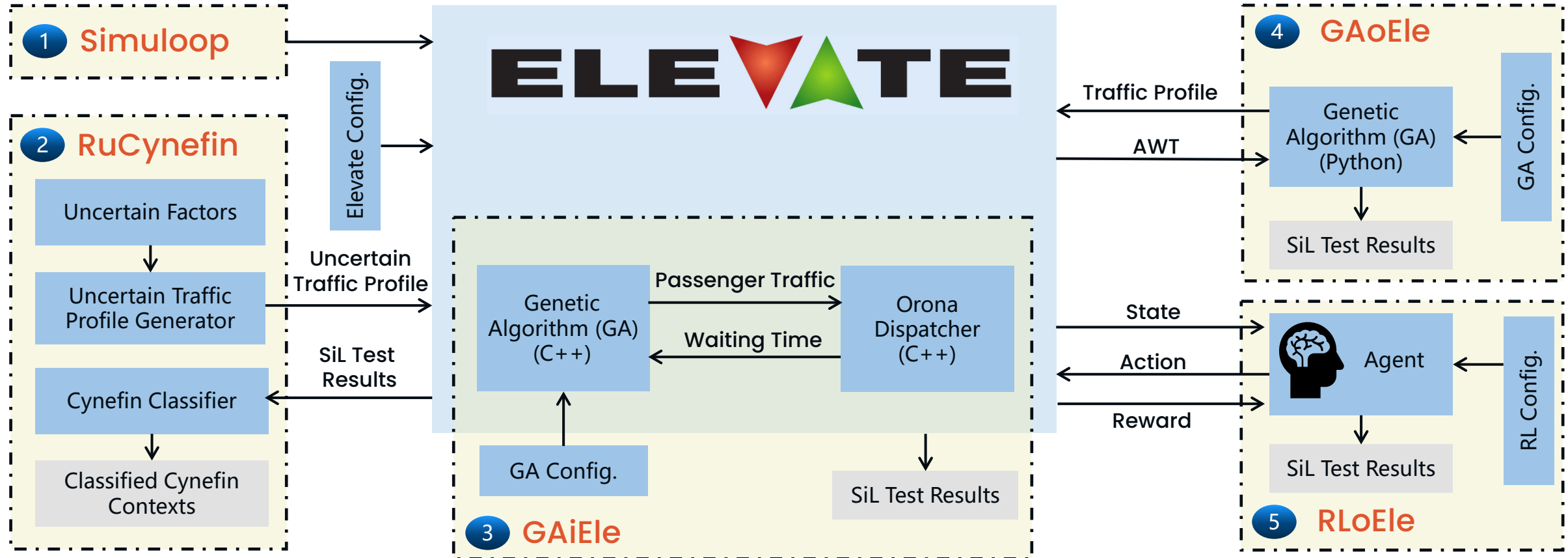
ANALYSIS DATA

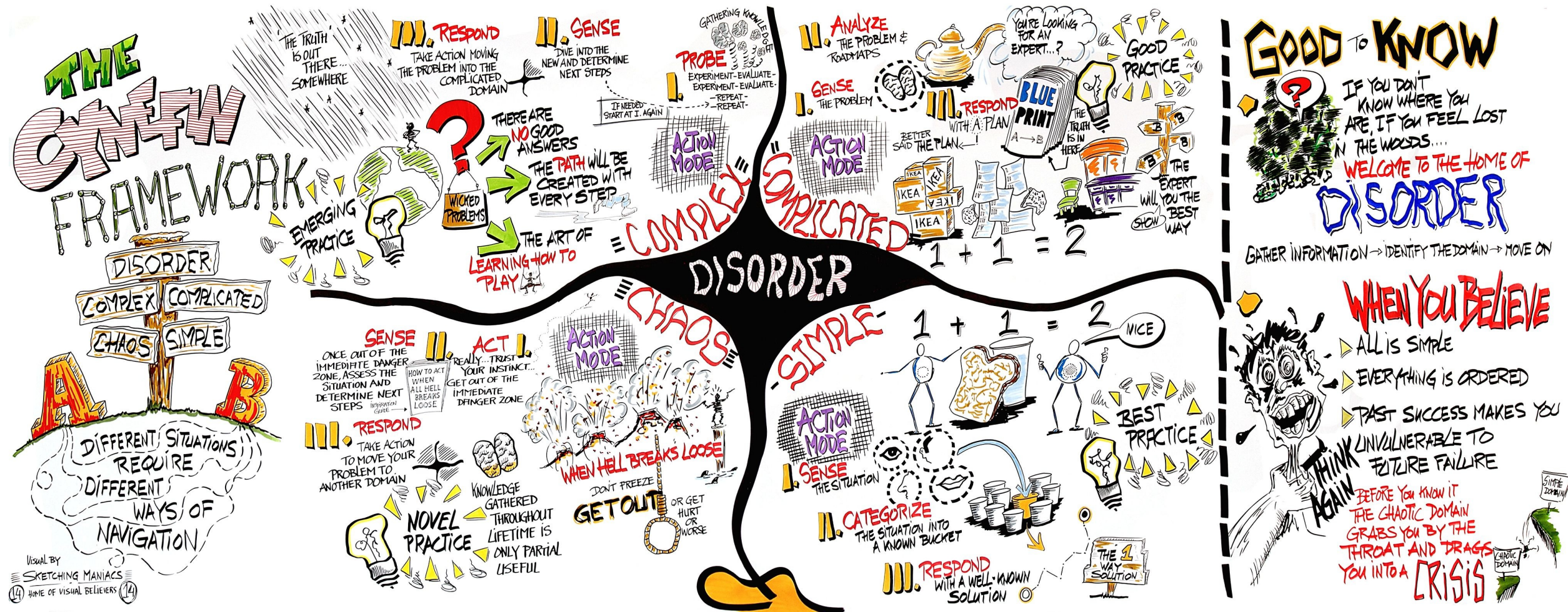
Analysis Type	Simulation
Measurement system	Metric
Dispatcher Algorithm	Group Collective Traffic mode: Up peak 1
Time slice between simulation calculations (s)	0.10
No of time slices between screen updates	10
No of simulations to run for each configuration	1
No of learning runs	0
Random number seed for passenger generator	1
Energy Model	Off

BUILDING DATA

Floor Name	Floor Level (m)	No of people	Area (m ²)	Area/person	Entrance Floor
Level 1	0.00	0	-	-	Yes
Level 2	3.80	50	-	-	No
Level 3	7.60	50	-	-	No

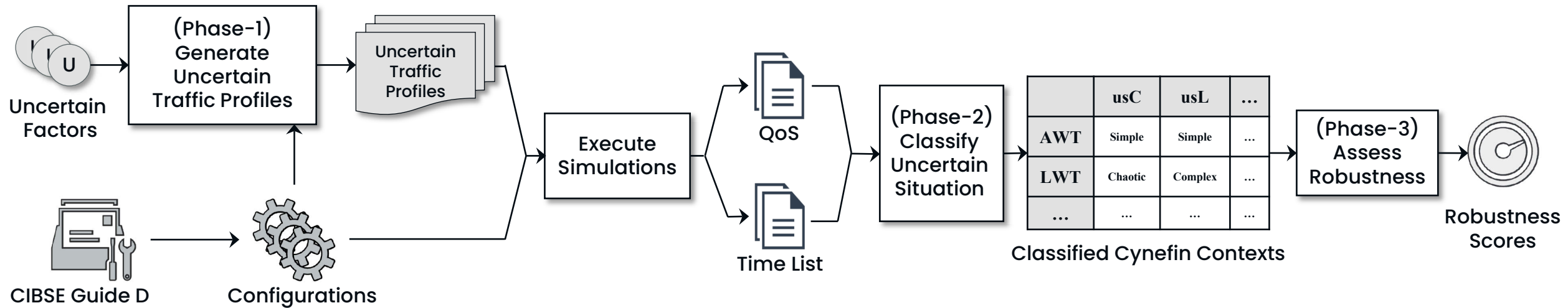
Our SiL-based Methods



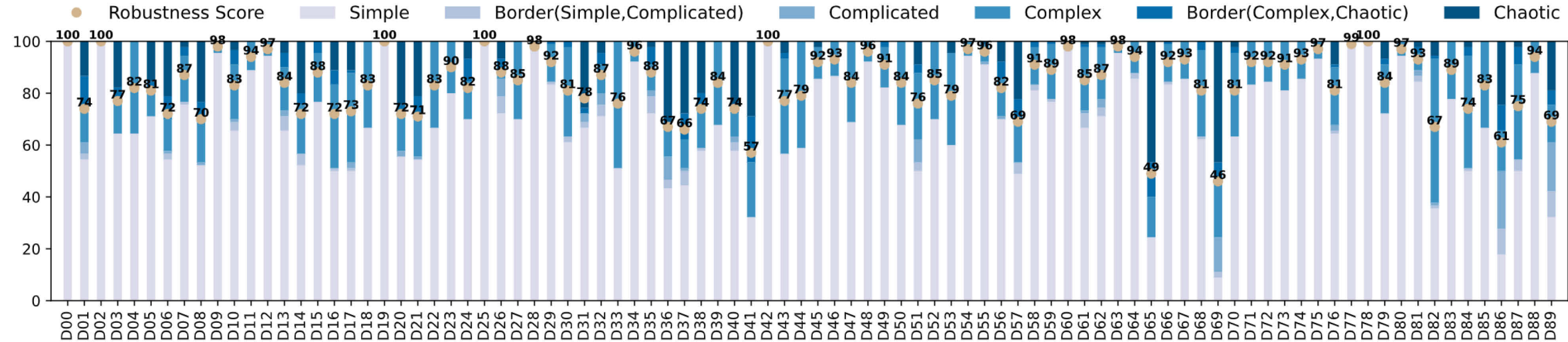


Sketch of the Cynefin framework, by Edwin Stoop

RuCynefin : Cynefin-based uncertain situation generation and classification

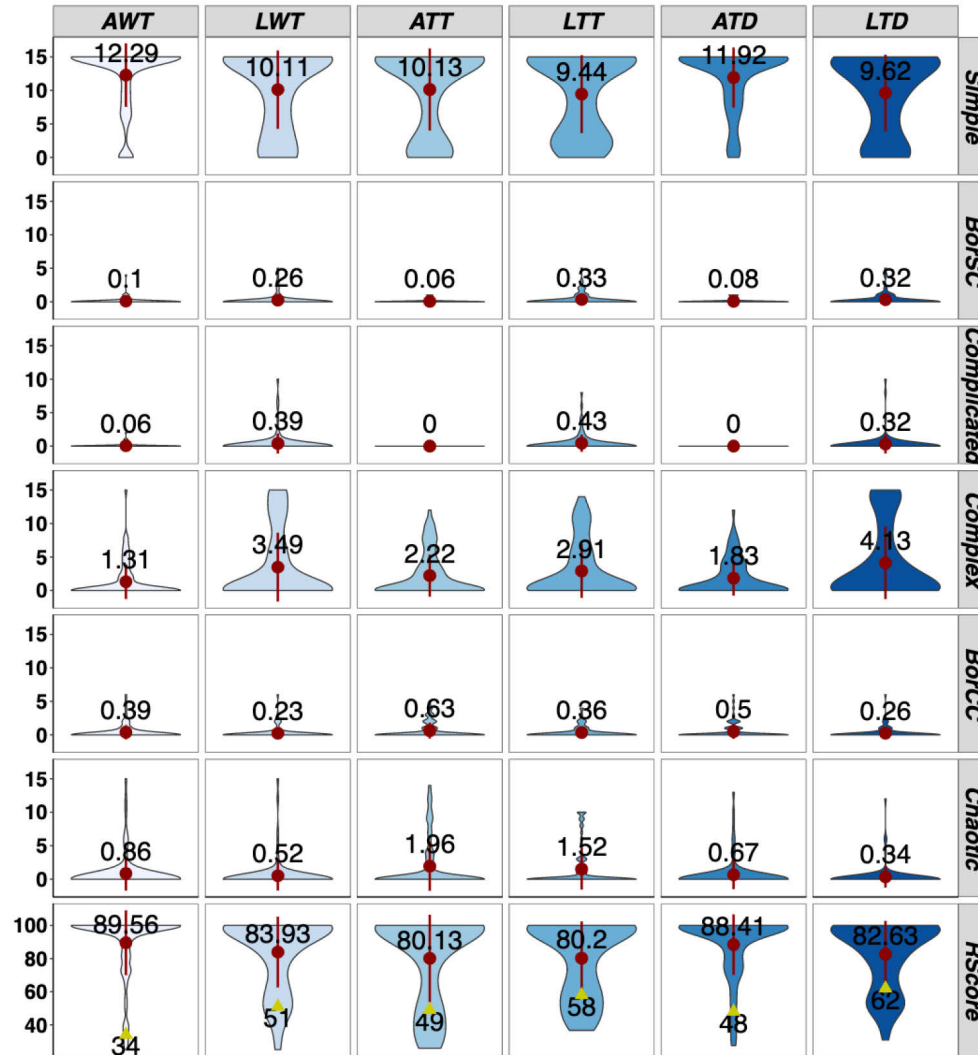


RuCynefin : Cynefin-based uncertain situation generation and classification



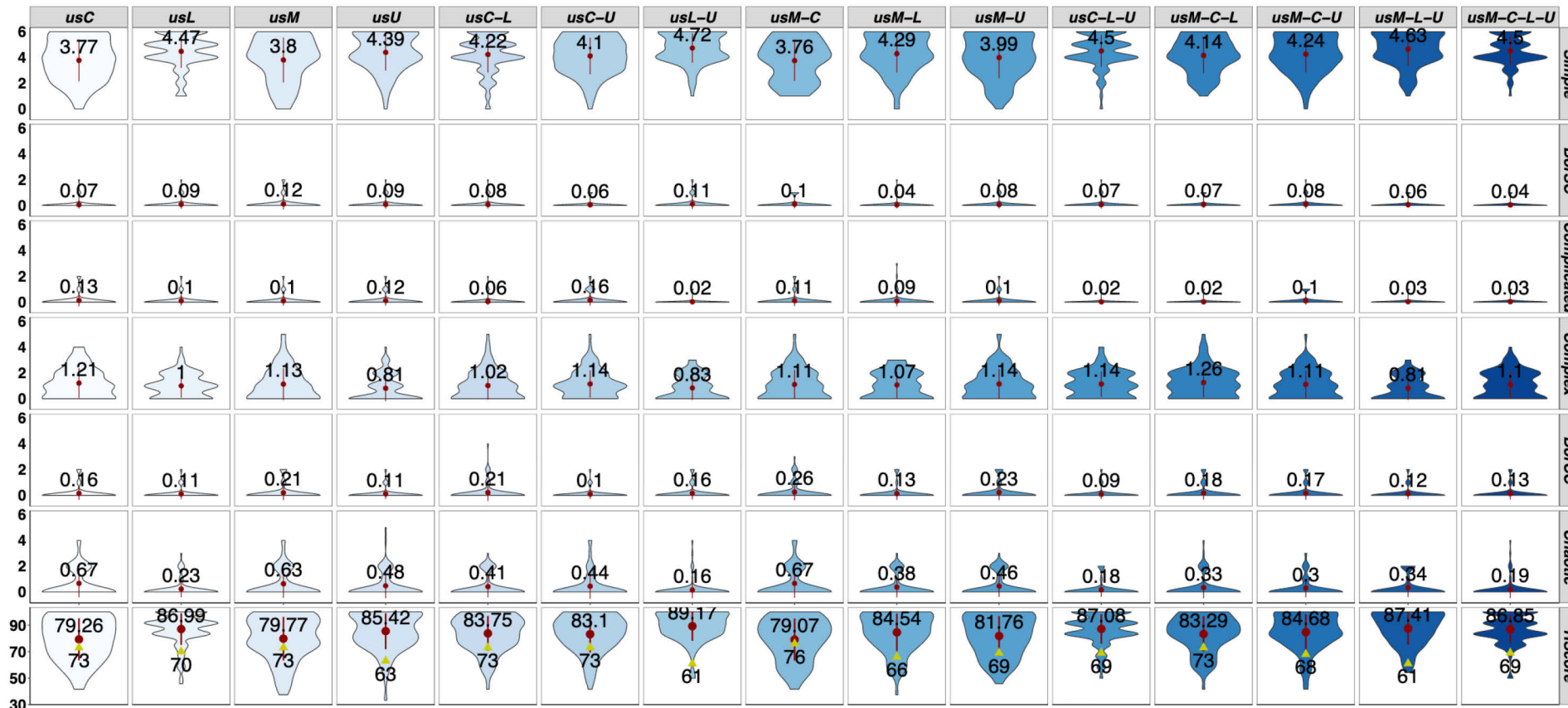
The 90 dispatchers exhibit diverse robustness in terms of dealing with uncertainties.

RuCynefin : Cynefin-based uncertain situation generation and classification



- AWT and ATD are impacted relatively less by uncertainties.
- Recommend to optimize a dispatcher's robustness under uncertainties with respect to a particular QoS of interest.

RuCynefin : Cynefin-based uncertain situation generation and classification



Different uncertain factors have different extents of impact on the robustness of the dispatchers.

Capacity Factor, Mass and their interaction have relatively higher impact on the dispatchers' robustness than the other uncertain factors.

RuCynefin : Cynefin-based uncertain situation generation and classification

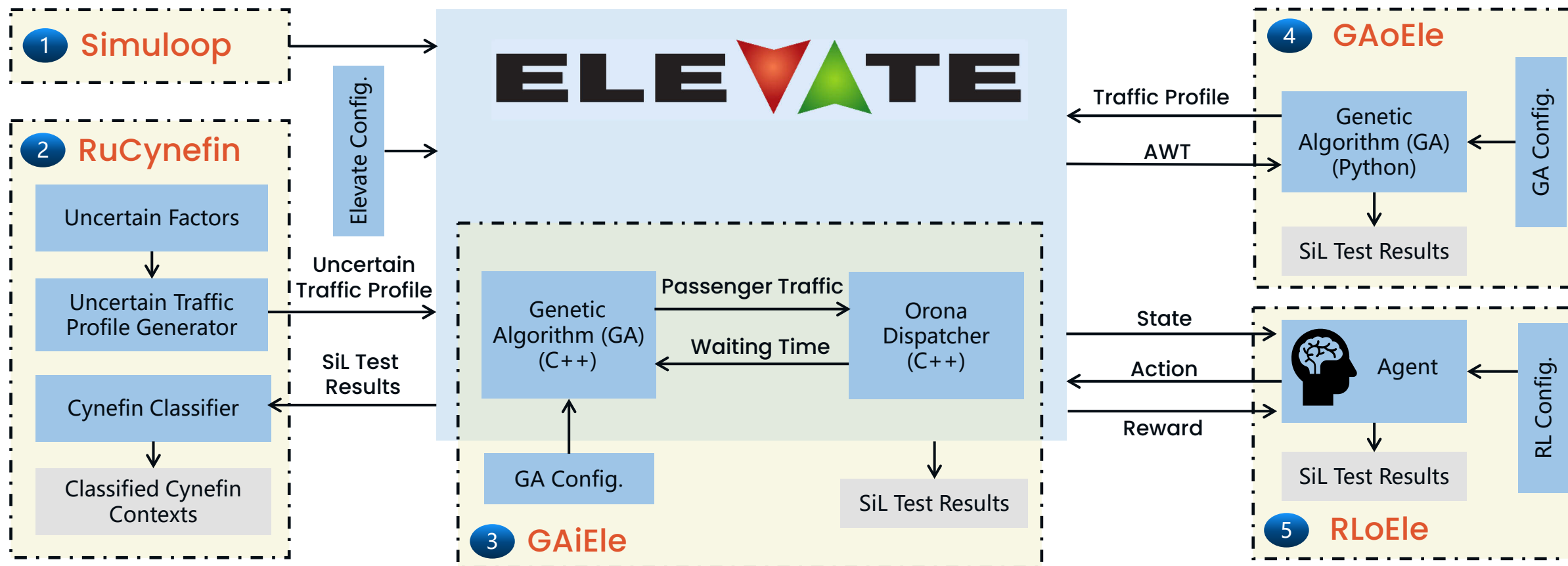
QoS	#1	#2	#3	#4	#5	#6	#7	#8	#9	#10	#11	#12	#13	#14	#15
AWT	69	69	73	76	75	71	73	73	76	72	77	76	74	76	76
LWT	57	57	59	62	62	62	61	59	63	59	62	58	59	68	62
ATT	55	64	51	60	59	57	69	52	61	56	65	62	63	71	67
LTT	51	66	43	59	50	60	74	50	55	53	58	55	62	59	55
ATD	60	80	64	74	76	64	78	58	75	62	82	68	71	79	82
LTD	47	66	52	64	58	55	70	46	56	57	61	54	53	64	63

#1 usC #2 usL #3 usM #4 usU #5 usC-L #6 usC-U #7 usL-U #8 usM-C #9 usM-L
#10 usM-U #11 usC-L-U #12 usM-C-L #13 usM-C-U #14 usM-L-U #15 usM-C-L-U

Provide feedback on which QoS against which uncertain situation should be prioritized for optimization.

- E.g., focus on LTD when facing uncertainties caused by Capacity Factor itself or its interactions with Mass.

Our SiL-based Methods

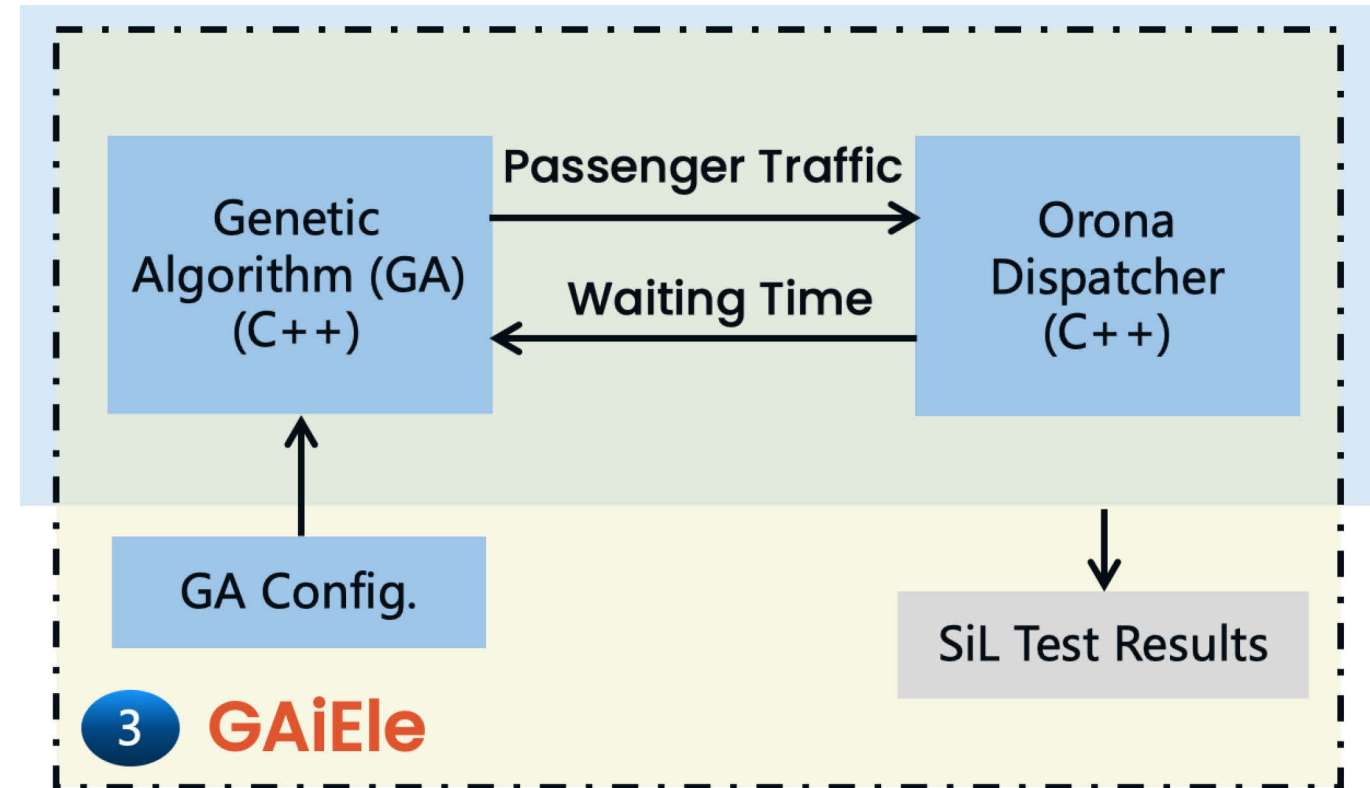
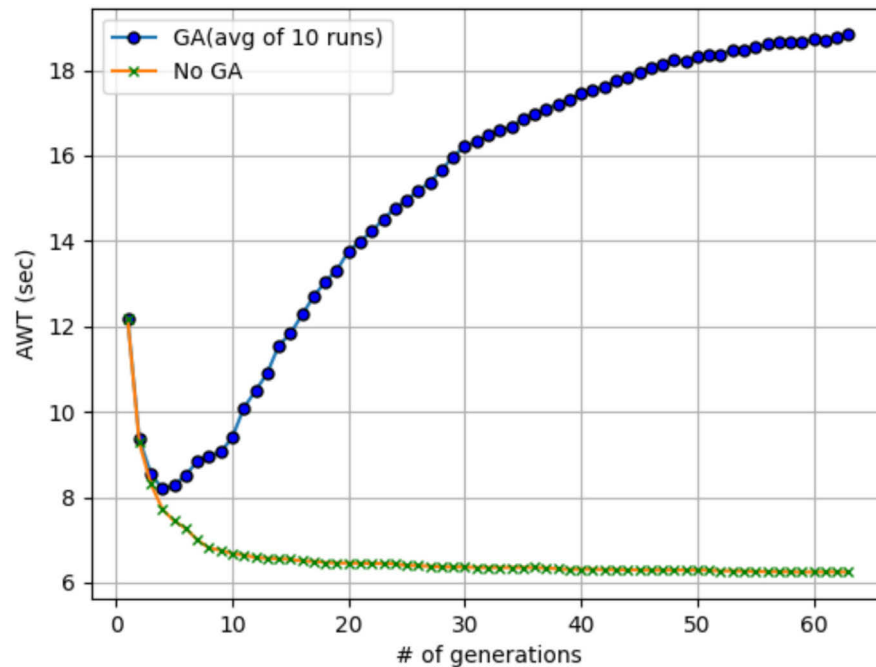


GAiEle: Search-based SiL testing

GAiEle generates passengers with specific attributes during SiL, for a given traffic profile, with GA, with the aim of maximizing AWT of passengers.

Arrival Time	Arrival Floor	Destination Floor	Mass	Capacity Factor	Loading Time	Unloading Time
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Empirical study:



GAoEle: Search-based SiL testing

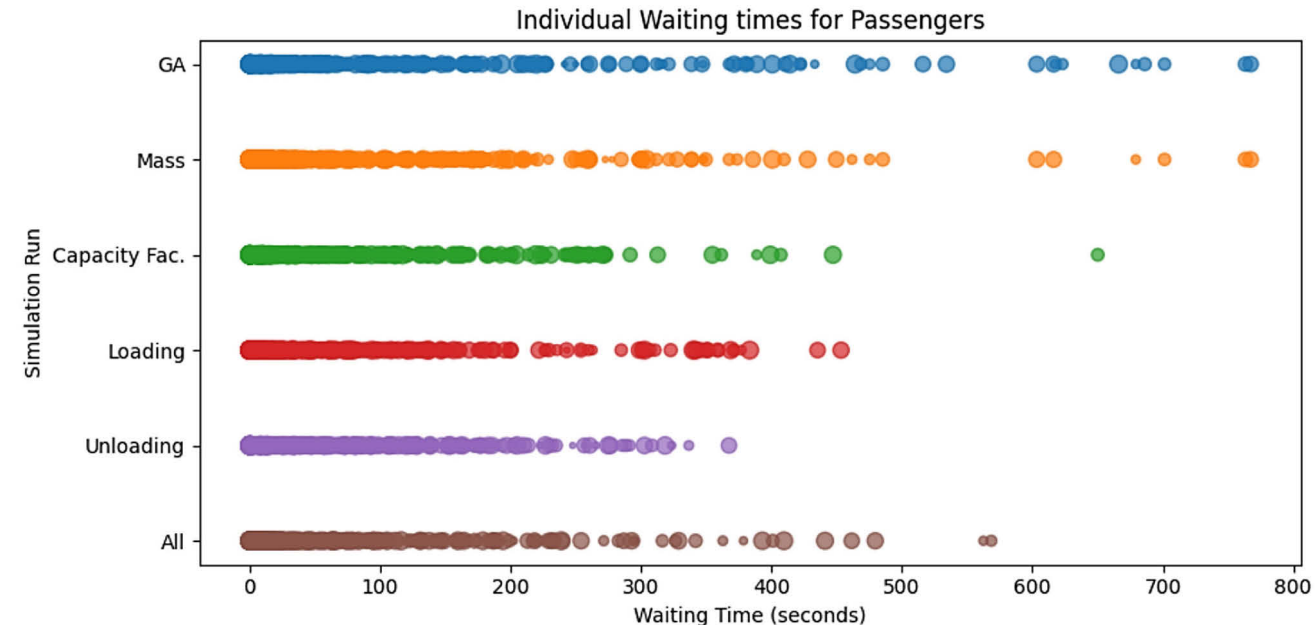
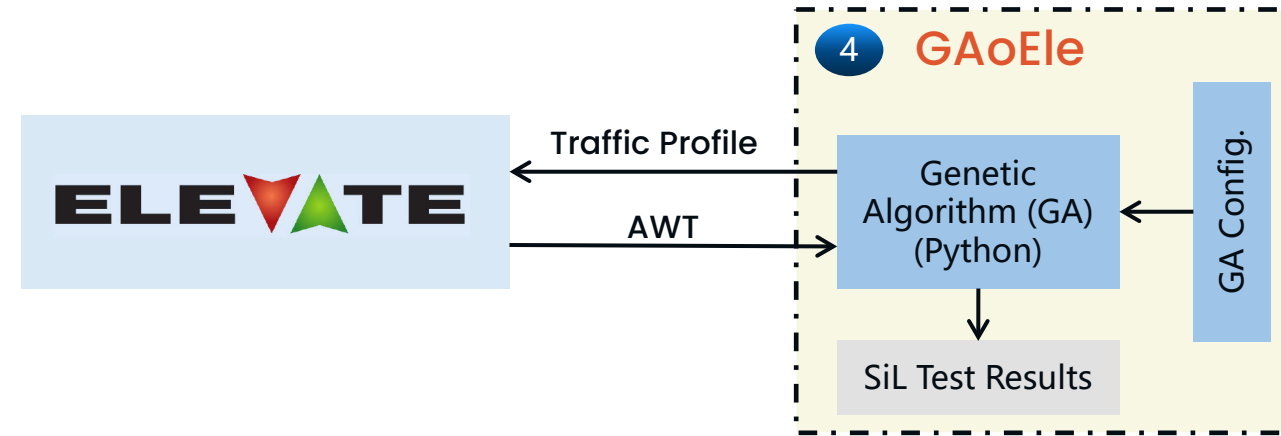
Objective: maximize AWT of passengers

Difference with GAIEle:

- load standard profile at the beginning
- change all passengers at each generation
- outside of Elevate, not extra engineering work

Empirical study:

Attribute	GA	Mass	Cap.	Load.	Unload.	All
Mass (kg)	x	90	x	x	x	90
Cap Fac. Mass (%)	x	x	75	x	x	75
Loading time (s)	x	x	x	2	x	2
Unloading time (s)	x	x	x	x	2	2
AWT(s)	44.5	40.3	39.0	34.0	30.3	34.5



RLoEle: Reinforcement learning based SiL Testing

Environment

- Building configuration
- Elevator setup

State

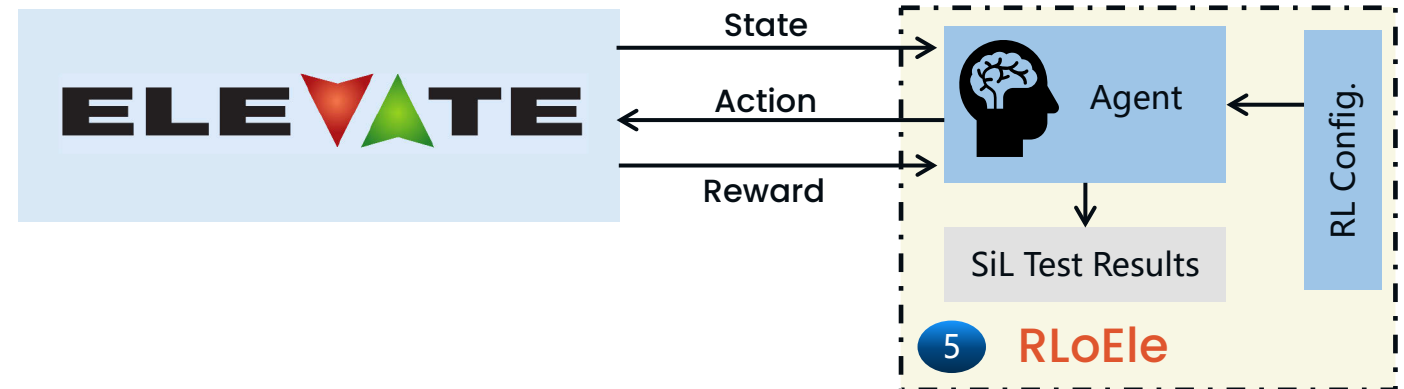
- Elevator and passenger positions and directions

Action

- Assign arrival and destination floors

Reward

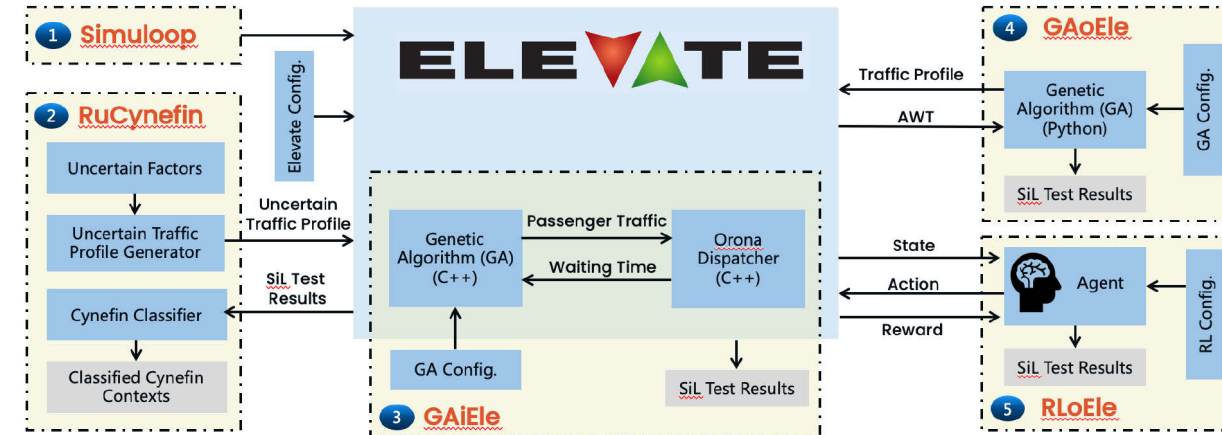
- AWT



Summary and Outlook

Follow-Up Works

- Industrial validation and technology transfer
- Generalize to other domains, e.g., train control



This work is supported by the **Adeptness** project funded by the European Union's Horizon 2020 programme. We thank **Orona** for providing us with industrial elevator dispatchers to perform this case study. We thank **Shaukat Ali, Liping Han, Joritz Galarraga, and Torbjørn Ruud** for their contributions to the work.



UiO :

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RLoELe: Reinforcement learning based SiL Testing

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State

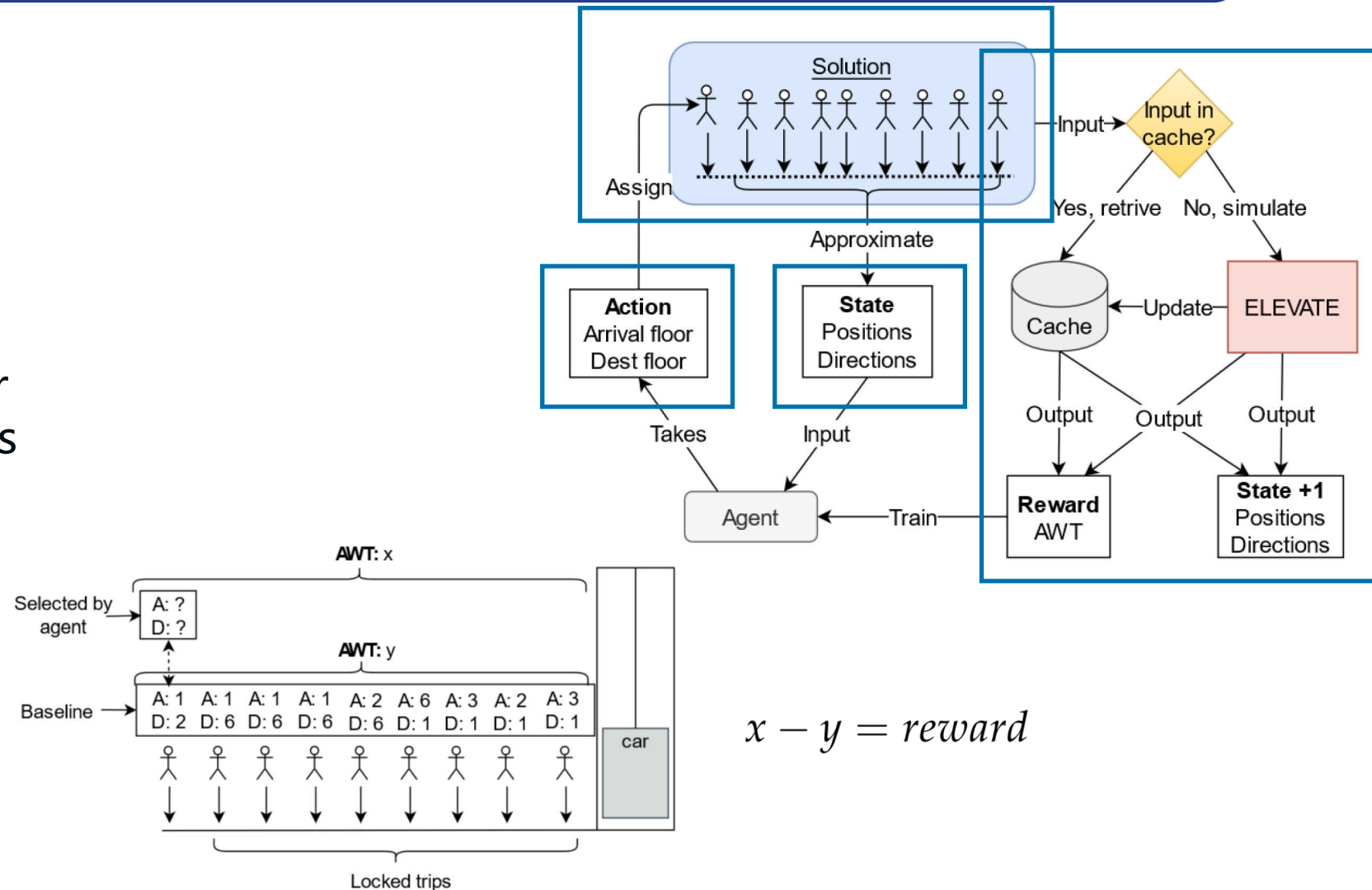
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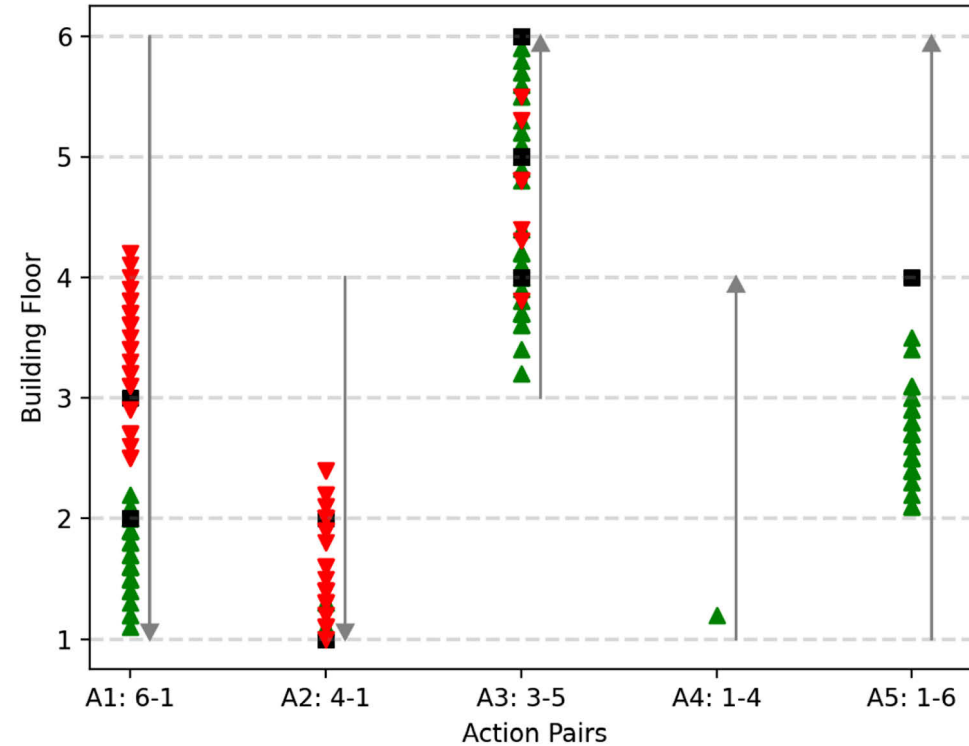
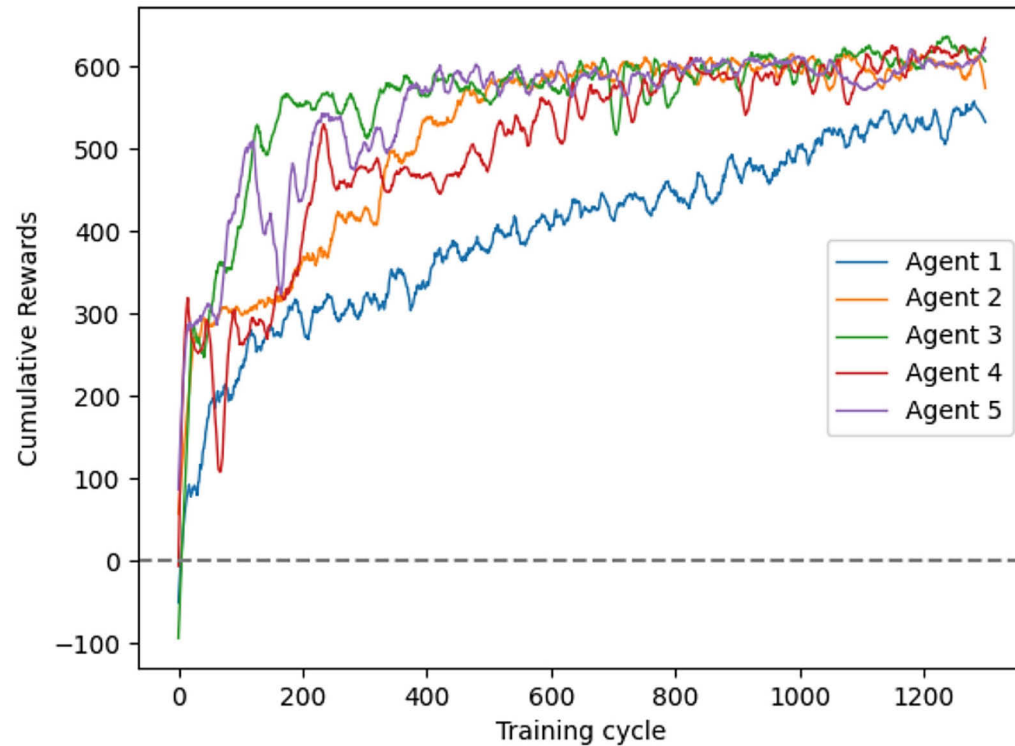
- Assign arrival and destination floors

Reward

- AWT



RLoELe: Reinforcement learning based SiL Testing



Most models were converged after 1000 cycles.

Given a floor height and a direction, it is straightforward to conclude which action to select.